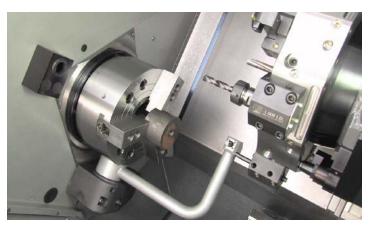
CNC Lathe Overview

Prof. Steven S. Saliterman Introductory Medical Device Prototyping Department of Biomedical Engineering, University of Minnesota http://saliterman.umn.edu/

Haas ST-10 CNC Lathe







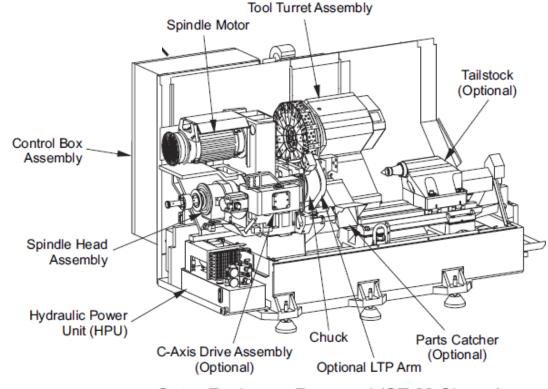
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Images courtesy of Haas

Safety Notice

- You must complete safety instruction before using tools and equipment in the Medical Device Center, ME Student Shop and CSE Workshops.
- All machinery can be dangerous. You must have a trained individual instruct you first when using unfamiliar equipment.
- > Only authorized and trained individuals may operate CNC equipment.
- Code examples shown are for illustration purposes only, and are not meant for operation or programming actual equipment. They may be incomplete or contain errors.
- Always abide by shop safety instructions and never engage in horseplay.
- Remember to wear OSHA approved eye protection in the shop, short sleeves, leather or steel toed shoes, and secure long hair, avoid loose clothing, and take off rings, watches and bracelets when using power equipment.
- These slides are part of the "Introductory Medical Device Prototyping" course at the University of Minnesota, and are not meant for any other purpose.
- Formal training in Haas is available from Productivity, Inc.

Lathe Design



Outer Enclosure Removed (ST-20 Shown)

Prof. Steven S. Saliterman

Image courtesy of Haas

Lathe Chuck and Tool Turret







ACTIVE PROGRAM - 000002	(CYCLE START TO SIMULATE)	INACTI
DODOOZ (LATHE OPERATION) ;		000
G80 G00 G40 G18 G99 ;		*000
G28 U0 ;		
G28 W0 ;		
T303 ; G50 S2000 ;		
G97 5400 M03 ;		
654 600 Z0.1 :		
X1.6 M08 ;		
696 5550 :		
G01 Z0, F0, 01 ;		
X-0.07 F0.007;		
600 X1.6 Z0.1 ;		
G71 P10 Q20 U0. 02 W5 D0. 0	B F0.01 ;	
N10 G42 G00 X0.5 Z0.1 F0.	01;	
G01 Z0. F0.004 ;		
X0.625; 603 X0.665 Z-0.02 R0.02;		
G03 X0. 665 2-0. 62 K0. 62 , G01 X0. 875 Z-0. 1819 ;		
G01 Z-0. 8484 ;		
601 X0.7 Z-1. ;		
7-1 25 :		
G02 X0.88 Z-1.34 R0.09;		
G01 X1.206;		
G03 X1.266 Z-1.37 R0.03;		
G01 X1.5 Z-1.5426 ;		
G01 Z-1.585; G01 X1.599;		000
N20 G40 G01 X1.6;		
670 P10 Q20 ;		2 99%
G97 5400 M03 ;		99%
EDITOR HELP (PRESS F1 TO NA	CLIPBOARD	

CNC Lathe Axis

- X is the back to front motion, with the *part* X0 being coincident with the Z axis. *Determines diameter.*
- Z is the spindle axis, and the *part* Z0 is normally the front finished face. *Determines location of faces, shoulders and grooves.*
- Home reference position movement at startup to extreme limits. A zero-return at POWER/STARTUP. This is the machine zero.
- We use a *floating zero* referred to as the *part zero* or *part origin*.
- We touch off the face and diameter, and store the offset from the machine zero in X and Z register of the *Tool Offsets Page*. (Not the same as mill which uses G54!)

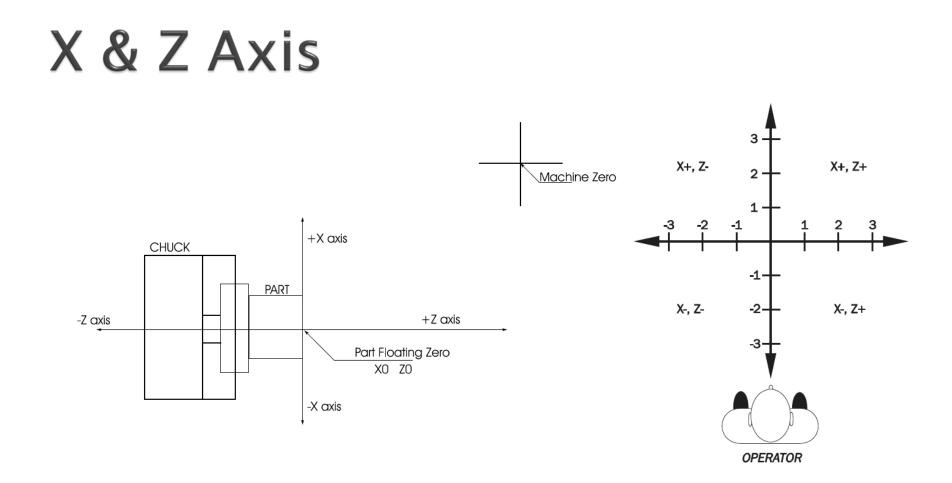


Image courtesy of Productivity and Haas

- Normally most of the X values are going to be positive in a part program. A negative X will occur only if you face a part past the centerline.
 - X values are in <u>diameters (not radius)</u>, hence a X1.0 will be moving the machine along the x-axis 0.5" in the positive direction.
- Z values will tend to be negative since zero is at the face. (Max. -1" travel beyond the spindle zero.)

Absolute & Incremental Positioning

- Absolute positioning: X and Z codes are based on the Zero point of the part.
 - If a diameter of 1.0000 inches is needed, you input X1.0000.
 - If you are facing a shoulder 0.3" back from the face of the part, Z-3.0000 is input.
- Incremental positioning: U and W based on current position of the machine.
 - So a change of U-.5000 would be a smaller diameter of 0.5" from where the machine is presently at.
 - A grooving tool moving back ¾" behind the previous groove would be input as W-.7500.
 - Also called point to point.
- Simultaneous moves are possible e.g. G01 X2.000 W-.25 Moves X in absolute and Z in incremental at the same time.

Optional Y Axis

An optional Y-axis moves tools perpendicular to the spindle center line. This motion is achieved by compound motion of the X-axis and Y-axis ball screws.

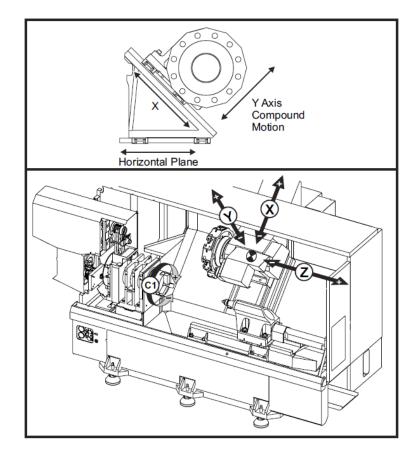
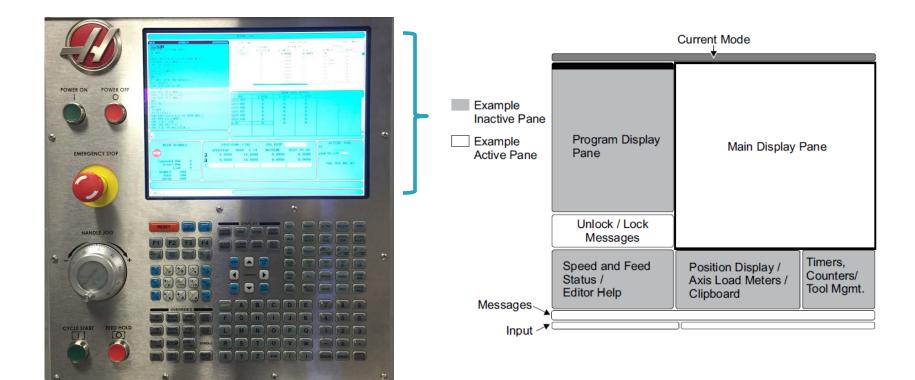


Image courtesy of Haas

Control Pendant with Display



Right Image courtesy of Haas

Keyboard Sections

Display buttons



Alpha buttons

Image courtesy of Haas

Powering On

Power On- Turns CNC machine on. All axis to machine zero X then Y.
 Power Off- Turns CNC machine tool off.

- Emergency Stop Stops all axis motion, spindle, tool changer and coolant pump.
- Jog Handle-Jogs axis selected; scroll through programs, menu items while editing and also altering feeds and speeds.

Cycle Start- Starts program in run mode or graphics mode.
 Feed Hold- Stops all axis motion. Spindle will continue to turn.
 Reset- Stops machine, will rewind program.
 Power Up/Restart- Axis will return to machine zero
 Recover- If a tool change is stopped in middle of a cycle an alarm will come up. Push the Recover button and follow the instructions to bring the tool change cycle to the beginning.

Setup – Tool Offset

Watch 12m

- 1. Tool (selected)) and work offset tables
- 2. Spindle, position and active tool figure.
- 3. ZERO RET, HAND JOG key mode buttons active

	IPS ON TOOL 1 SPINDLE 2 3	COOLANT POSITION 0	H(LEN GEOMETRY	IGTH) WEAR	D(DI	(A)
		0		WEAR	CEONETRY	
	1 SPINDLE 2 3				GEOMETRY	WEAR
	23		7.0000	0.0001	0.	0.
	1 3	θ	5.0000	0.	θ.	θ.
		0	5.0000	0.	0.	0.
	4	0	5.0000	0.	0.	0.
	2	0	5.0000 5.0000	θ. θ.	θ. θ.	0. 0.
	7	0	5,0000	θ.	0.	0.
	8	0	5.0000	θ.	0.	θ.
	9	0	5.0000	0.	0.	0.
		1				
			WORK ZER	0 OFFSET		
	G CODE	X AXIS	Y AXIS	Z AXIS		
	G154 P94	0.	0.	0.		
	G154 P95	0.	θ.	θ.		
	G154 P96	0.	0.	θ.		
	G154 P97	0.	0.	θ.		
	G154 P98	0.	0.	0.		
	G154 P99	0.	θ.	0.		
	G 92	0.	0.	0.		
]		- and the second			
MAIN SPINDLE POS	SITION: (IN)	JOG I	RATE 0.	0010	ACTIVE	TOOL
OPERATO	R WORK G	54 MACH		TO GO	11	
			. 0000		LOAD 50 LIFE	100%
				0.0000	SHELL	
onmanded RPM: 0 🗹 0.00	900 10.0	000 0.	. 0000	0.0000		
Actual RPM: 0 Z 0.58	363 10.6	063 0.	. 5863	0.0000		
Load: 0						
PINDLE: 100%						
FEED: 100%						
RAPID: 100%						
				RY RUN		

Edit

- 1. Provides two program editing panes.
- 2. Allows program editing, management, and transfer functions.
- 3. EDIT, MDI/DNC, LIST PROG buttons active

TIVE PROGRAM - 001234 (CYCLE START TO SIMULATE)	
201821 G00 G17 G40 G49 G90 G80 G98; G00 G51 Z0; 11 M06; S1000 M03; G00 G51 Z0; G00 G90 G54 X=0.35 Y=0.25; G01 Z=0.375 F50.; x=0.25 F10.; y3.5; G02 X0.5 Y4.25 I0.75 J0; G01 X3.5; G02 X4.25 Y3.5 I0 J=0.75; G01 Y0.5; X4.25; G03 X3.5 Y=0.25 I0 J=0.75; G01 Y0.5; G00 53 Z0 M05; H01; '12 M06; G00 G54 X1.25 Y1.25; S967 M03; G13 I0.3 X1. 00.1 Z=-0.25 D02 F12.6; G13 I0.3 X1. 00.1 Z=-0.25 D02 G00 Z1; G00 Z1; G00 Z1; G00 Z1; G00 Z1; G00 Z1; G22; C5 Y2; Z5; G0	IMACTIVE PROGRAM 000024 (22X1 CLASS VF-2 CORNER CHAMF+R) 000035 (INSERSOL 4140 STEEL DEMON CS9.) * 201234 001234 764 BYTES 56 BLOCKS 3 PROGRAMS
Gold Coll To. 3' KL. 00.1 Z0.05 D02 L5 F12.6 ; GOB COB ZL. W09 ; EDITOR HELP (PRESS F1 YO NAVIGATE) HELP-HOW TO USE THE EDITOR CONTENTS 1) General 2) Dual-screen design 3) Pop-up menu 4) Context sensitive help 1) General 1) General <th>98% FREE (987670 BYTES)</th>	98% FREE (987670 BYTES)

Operating

- 1. Provides all control features necessary to make a part.
- 2. MEM button active

G01 Y=0.25; 1000 X=0.35; 1 SPIN G00 Z01 H09; 2 M01; 3 ;1 M06; G00 G53 Z0 M05; 3 M01; 5 ;00 G90 G54 X1.25 Y1.25; 5 S967 M03; 0, 1 Z=0.25 D02 F12.6; G13 10, 62 Z=0.25 D02 F12.6; 8 g00 G20 C1.; 2, 75; 9 10 w 10	L	COOLANT POSITION 0 0 0 0	PROGRAM TO H(LEN GEOMETRY 7,0000 5,0000		GEOMETR 0.	
G03 x3.5 y-0.25 10 3-0.75 ; 1000 G01 y-0.25 ; 1 y-0.75 ; G02 (31 y-0.25 ; 1 y-0.75 ; G02 (32 0 M05 ; 1 y-0.75 ; G02 (32 0 M05 ; 1 y-0.75 ; G03 (31 y-0.25 ; 1 y-0.75 ; G03 (31 y-0.25 y-0.25 D02 F12.6 ; 1 y-0.75 ; G13 10.6 25 z-0.25 D02 F12.6 ; 1 y-0.75 ; G03 (11 y-0.75 ; 9 y-0.75 ; MAIN SPINDLE MAIN SPINDLE MAIN SPINDLE 0 CHTP LOAD 0.0 POPON Q CHTP LOAD 0.0 POPON Q CHTP LOAD 0.0 POPON Q CHTP LOAD 0.0 POPON		POSITION 0 0 0	GEOMETRY 7.0000 5.0000	WEAR 0.0001	0.	
G01 (7-9, 25 ; X-0, 35 ; G00 (53 20 M05 ; H01 ; 12 M06 ; G00 (53 20 M05 ; H01 ; 13 10, 3 K1, 25 Y1, 25 ; S07 M03 ; G00 (21, 25 Z-0, 25 D02 F12, 6 ; G00 (21, 25 Z-0, 25 Z-0, 25 D02 F12, 6 ; G00 (21, 25 Z-0, 25 Z-0, 25 Z-0, 25 D02 F12, 6 ; G00 (21, 25 Z-0, 25		0 0 0	7.0000	0. 0001	0.	
C00 250.1 M09; C00 253 20 M05; N01; ; C00 253 20 M05; N01; ; C00 259 254 XL.25 YL.25; S967 M03; C13 10.625 Z-0.25 D02 F12.6; C13 10.625 Z-0.25 D02 F12.6; C00 21.; X2.75; MAIN SPINDLE MAIN SPINDLE MAIN SPINDLE MAIN SPINDLE MAIN SPINDLE MAIN SPINDLE MAIN SPINDLE MAIN SPINDLE MAIN SPINDLE 0 SURF SPD: 0.0 KW 0 SURF SPD: 0.0 FFM 0 SINF SPD: 0.0		0 0	5.0000	0.		0.
M01; 12 M06; 500 C90 C54 X1.25 Y1.25; 5967 M03; C13 T0.3 K1. 00.1 Z-0.25 D02 F12.6; C13 T0.3 K1. 00.1 Z-0.25 D02 F12.6; C00 Z1.; 22,75 Y2.75; ■ MAIN SPINDLE MAIN SPINDLE MAIN SPINDLE MAIN SPID: 0.0 KW SURF SPD: 0 FPM 0 CHTP LOAD: 0.00000 7					0.	0.
12 M06; 4 G00 G54 X1. 25 Y1. 25; 5 G13 10. 625 C02 F12. 6; 6 G13 10. 625 C02 F12. 6; 7 G00 C11. 1; X2. 75 9 10 MAIN SPINDLE MAIN SPINDLE MAIN MAIN SPINDLE 0 CHIP LOAD: 0.00000 7 GURF SPR: 0 GPON 7		0	5.0000	0.	0.	0.
G00 c90 c54 XL.25 YL.25 ; 3 G13 10.3 KL 00.1 Z-0.25 D02 F12.6 ; 6 G13 10.6 25 Z-0.25 D02 F12.6 ; 7 G00 c11. ; 8 X2.75 Y2.75 ; 9 MAIN SPINDLE 9 MAIN SPINDLE MAIN SPINDLE SPEED(RPM) SD LD: 0.0 KW GURF SPR: 0 FPM G GURF SPR: 0 6 PPM 3 GURF SPR: 0 6 PPM 7			5.0000	θ.	θ.	0.
\$967 M03 ; 6 (13 10.3 KL. 00.1 Z-0.25 D02 F12.6 ; 7 (13 10.525 Z-0.25 D02 F12.6 ; 8 (500 ZL. ; 9 10 10 WAIN SPINDLE 9 MAIN SPINDLE MACHI SPEED(RPM) SP LD: 0.0 KM 0 SURF SPD: 0 0 0 CHIF LOAD: 0.00000 7		0	5.0000	0.	θ.	θ.
G13 10.6 25 -0.2 5 002 F12.6 ; 7 G13 10.6 25 2-0.2 5 002 F12.6 ; 8 G00 21. ; 8 x2.75 y2.75 ; 9 10 10 MAIN SPINDLE MAIN SPINDLE SPEED(RPM) SD LD: 0.0 KW GUP OF CHIP LOAD: 0.00000		0	5.0000	0.	0.	0.
C00 21. : 8 Y2. 75 ; 9 IO 10 MAIN SPINDLE MAIN SPINDLE SDEED(RPH) SP LD: 0.0 KW GOOD SUPERSTR: 0 FPM O CHUP LOAD: 0 POPON 7 7		θ	5.0000	0.	0.	0.
X2.75 Y2.75 ; 9 10 MAIN SPINDLE MAIN SPINDLE SPEED(RPH) SP LD: 0.0 KM 0 SURF SPD: 0 FPM 0 CHIP LOAD: 0.00000 7		0	5.0000	0.	θ.	θ.
MAIN SPINDLE MAIN SPINDLE SPEED(RPH) SP LD: 0.0 KW SURF SPD: 0 FPH 0 CHIP LOAD: 0.00000 7		θ	5.0000	θ.	0.	0.
MAIN SPINDLE MAIN SPINDLE STOP SPEED(RPH) SPLD: 0.0 KW SURF SPD: 0 FPH 0 CHIP LOAD: 0.00000 7		0	5.0000	0.	θ.	0.
STOP SPEED(RPM) SP LD: 0.0 KW MACHI STOP SURF SPD: 0 FPM M M M θ CHIP LOAD: 0.00000 7 M M M	ION:	(IN)		LOAD	TIMERS	S & COUNTERS
STOP SPELUCRARY SURF SPD: 0 FPM U CHIP LOAD: 0.00000				0%	THIS CYC	LE 0:00:00
0 CHIP LOAD: 0.00000 7		0000		1993	LAST CYCL	LE 0:00:23
CHIP LORD: 0.00000 7	Θ.	0000		Θ %	REMAINING	G 0: 00: 23
	Θ.	5863		0%	NEO COUNT	
LOAD(%) 0% ACT FEED: 0.					M30 COUNT	
GEAR: LOW					MACRO LAB	TOPLE HEATINGS
100% FEED 100% BAPID 100%					MACRO LAB	
SPINDLE 100% FEED 100% RAPID 100%	_				<u> </u>	
				DRY RUN		

Pendant Front Panel

Power On - Turns the machine on.



Power Off - Turns the machine off.



Emergency Stop - Large red button with a yellow bezel. Press to stop all axis motion, disable servos, stop the spindle and tool changer, and turn off the coolant pump. Turn to reset.



Jog Handle - This is used to jog axes (select in Hand Jog Mode). Also used to scroll through program code or menu items while editing.



Cycle Start - Starts a program. This button is also used to start a program simulation in Graphics mode.



Feed Hold - Stops all axis motion. Press Cycle Start to cancel. Note: The spindle will continue to turn during cutting.

Jog Mode

- Jog Mode allows you to jog each of the axes to a desired location. Before jogging the axes it is necessary to home (beginning axes reference point) the axes. (ZERO/RET AND AUTO/ALL AXES OR HOME/G28)
- To enter jog mode press HANDLE JOG, then press the desired axis (e.g. X, Z, etc.) and either use the handle jog keys or the jog handle to move the axis.
- There are different increment speeds that can be used while in jog mode; .0001, .001, .01 and .1.

Function Keys

- □ F1 F4 Keys –Different action in Editing Program and Offset mode.
- X Dia Mesur (X Diameter Measure) Record X-axis tool shift offsets on the offset page during part setup.
 Next Tool Next tool from the turret (usually used during part setup).
- X/Z Toggle between X-axis and Z-axis jog modes during part setup.
- □ Z Face Measur (Z Face Measure) Record Z-axis tool shift offsets on the offset page during part setup.

Jog Keys

- Chip FWD (Chip Auger Forward) Move chips out of the machine.
- **Chip Stop** (Chip Auger Stop) Stops auger movement.
- Chip REV (Chip Auger Reverse) Starts the optional chip auger in the "Reverse" direction.
- X/-X and Z/-Z (axis keys) Manually jog axis by holding down the individual key or pressing the desired axes and using the jog handle.
- Rapid When pressed simultaneously with one of the above keys (X+, X-, Z+, Z-), that axis will move in the selected direction at maximum jog speed.

<- TS - Pressing this key moves the tailstock towards the spindle.
 TS Rapid - Increases the speed of the tailstock when pressed simultaneously with one of the other tailstock keys.
 -> TS - Pressing this key moves the tailstock away from the spindle.
 XZ (2-Axis) Jogging

Override Keys

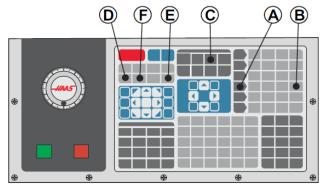
- 10 Decreases current feed rate by 10%.
 100% Sets control over ride feed rate to programmed feed rate.
- \square +10 Increases current feed rate by 10%.
- -10 Decreases current spindle spéed by 10%.
 100% Sets overridden spindle speed to programmed speed.
- \square +10 Increases current spindle speed by 10%.

Manual Tool Offset

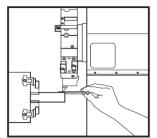
Manual offset entry:

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- 1. Load a tool into the tool turret.
- 2. Press the HANDLE JOG key (A)



- 3. Press .1/100. (B) (The lathe will move at a fast rate when the handle is turned).
- 4. Toggle between the X and Z jog keys until the tool is touching the side of the part at about a 1/8 of an inch from the front edge.
- 5. Place a sheet of paper between the tool and the part. Carefully move the tool as close as possible while still able to move the paper.



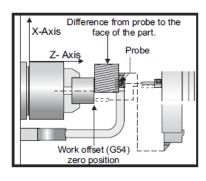
Images courtesy of Haas

- 6. Press OFFSET (C), until the Tool Geometry table is displayed.
- 7. Press X DIA MESUR (D). The control will then prompt for the diameter of the part. This will take the X position located in the bottom left of the screen and the diameter of the part and put it with the position of the tool.
- 8. Back the tool from the part and position the tool tip so that it is touching the face of the stock.
- 9. Press Z FACE MEAS (E). This will take the current Z position and write it to the tool offset.
- 10. The cursor will move to the Z-axis location for the tool.
- 11. Press NEXT TOOL (F).

Setting Part Zero

- Part Zero is a user defined reference point that the CNC control will use to program all moves from.
- Select Tool #1 by pressing MDI/DNC, enter "T1" and press TURRET FWD.
- Jog X and Z until the tool is just touching the face of the part.
- Press Z FACE MEAS to set part zero. a

Tool Pre-Setter





- Alternative to manually recording tool offsets.
- Each tool is "touched-off" on a probe.
- After that, only one tool is touched off on the part's zero position, and work offsets are automatically set for all tools.
- > When the probe is down, axes can only be moved with handle jog.
- Once the probe is touched, the control will beep, the turret will halt, and the position of the tool will be stored typically in G54.
- Faster than manual method.

Image courtesy of Haas

Automatic Tool Setting Probe

- The probe is first set up for tooling in manual mode, where initial tool measurements are made.
- After this setup, automatic mode is available to reset offsets when inserts are changed.
- Tool break detection is also available to monitor tool wear and breakage.
- The software generates G code which can be inserted into lathe programs to enable probe use during automatic operation.
- First press MDI/DNC and then PRGRM CONVRS to access the IPS tabbed menu set. Use the right cursor key to navigate to the PROBE tab and press WRITE/ENTER.

Probe Menu

Menu Item	Explanation
OP MODE	Use the left and right cursor arrow keys to choose between Manual, Automatic, and Break Detect modes.
TOOL NUMBER	The tool number to be used. This value automatically sets to the current tool position in Manual mode. It can be changed in Automatic and Break Detect Modes.
TOOL OFFSET	Enter the tool offset number that is being measured.
TOOL TIP DIR	Use the left and right cursor arrow keys to choose the tool nose vector V1-V8. See "Tool Tip Direction" for more information.
TOLERANCE	Sets the measurement difference tolerance for Break Detect mode. Not available in other modes.
X OFFSET, Z OFFSET	Displays the offset value for the specified axis. Read only.

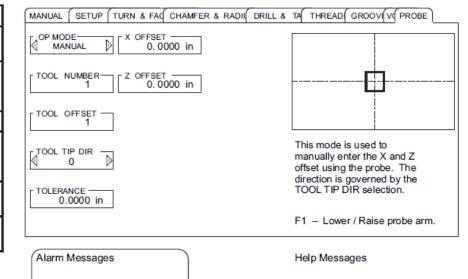
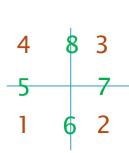
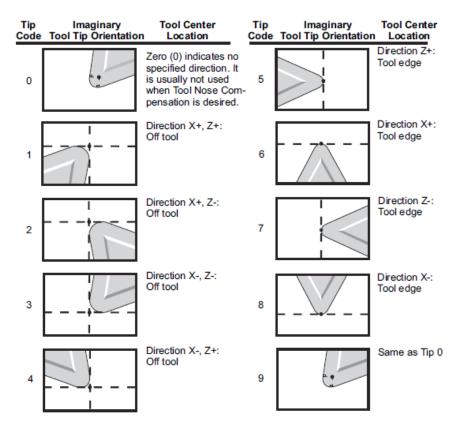


Image courtesy of Haas

Tool Tip Direction





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Image courtesy of Haas

Steps: First Manual Mode...

- 1. Tools must be touched off in manual mode before automatic mode can be used.
- 2. Enter the probe menu by pressing MDI/DNC, then PRGRM CONVRS, and selecting the Probe tab. Press F1 to lower the probe arm.
- 3. Select the tool to be touched off using TURRET FWD or TURRET REV.
- 4. Select Op Mode "Manual" using the left / right cursor arrow keys, then press WRITE/ENTER or the down cursor arrow key.
- 5. The tool offset option is set according to the currently selected tool position. Press WRITE/ENTER or the down cursor arrow key.
- 6. Type the tool offset number to be used, then press WRITE/ENTER. The offset number is entered and the next menu option, Tool Tip Dir, is selected.

- 7. Use the left / right cursor arrow keys to select a tool tip direction, then press WRITE/ENTER or the down cursor arrow key. See the "Tool Tip Direction" section for more information on this topic.
- 8. Use the jog handle to move the tool tip to within approximately 0.25" (6 mm) of the tool probe in the direction indicated by the on-screen tool tip direction diagram. Note that if the tool tip is too far from the probe, the tool will not reach the probe and the operation will alarm out.
- 9. Press CYCLE START. The tool tip is touched off and offsets are recorded and displayed. A G code program for the operation is generated in MDI and is used for tool movement.
- 10. Repeat steps 1–7 for each tool to be touched off. Be sure to jog the tool turret away from the probe before selecting the next tool position.
- 11. Press F1 to raise the tool arm.

Then Automatic Mode...

- 1. Use the left / right cursor arrow keys to select a tool tip direction, then press WRITE/ENTER or the down cursor arrow key. See the "Tool Tip Direction" section for more information on this topic.
- Use the jog handle to move the tool tip to within approximately 0.25" (6 mm) of the tool probe in the direction indicated by the on-screen tool tip direction diagram. Note that if the tool tip is too far from the probe, the tool will not reach the probe and the operation will alarm out.
- 3. Press CYCLE START. The tool tip is touched off and offsets are recorded and displayed. A G code program for the operation is generated in MDI and is used for tool movement.
- 4. Repeat steps 1–7 for each tool to be touched off. Be sure to jog the tool turret away from the probe before selecting the next tool position.
- 5. Press F1 to raise the tool arm.

Mode Keys

o Edit

- Used to make changes in a program stored in memory. When you
 press EDIT two panes appear at the top of the screen. In the left pane
 the active program appears. In the right an inactive program appears
 or the select program screen appears.
- On the bottom left a editor help pane appears and on the right a clipboard pane. Editing may be performed in either the active or inactive panes.
- Pressing EDIT toggles between the two panes, (changes background to white). To call up a program from memory and put it in one of the edit panes press SELCT/PROG. Highlight the program desired by using the up or down cursor buttons and press WRITE/ENTER.
- In the edit mode you are able to use the edit keys in the same row as the EDIT key.

- Insert Enters commands keyed into the input panel in lower left pane of CRT after the cursor highlighted word in a program.
- Alter Highlighted words are replaced by text input into the input panel.
- **Delete** Highlighted words are deleted from a program. Will undo up to the last 9 edit changes.
- F1 key While in the edit mode pressing FI will bring up an edit pop up window. Using the sideways cursor buttons will toggle thru HELP, MODIFY, SEARCH, EDIT AND PROGRAM MENUS. The up and down buttons will cursor thru the different options in each of the above.
 Modify Gives options on changing line numbers.

Programs

- A block is a series of words on a single line ended with a ";" also known as the end-of-block (EOB) symbol.
 - Leading zeros and + signs are not needed.
 - Modal commands with G, X, Z,F, S, T and M need not be repeated in the following blocks unless a different word or change of value is needed.
 - Only one M code at the end of the block is permitted.
- Preparatory "G" codes make the tool do specific operations.
- "M" codes cause action to occur at the end of the block. Always executed last.
- N1-N9999 are optional sequence (line) numbers especially useful in macro subroutine.
- Programs begin and end with "%".
- The second line is the title of the program. Format is "O" followed by 5 digits.
- Enter comments by enclosing in parenthesis.
- A forward slash "/" denotes an optional block. BLOCK DELETE will skip these lines when running.

Subroutines

- Subroutines (subprograms) are usually a series of commands that are repeated several times in a program. Instead of repeating the commands many times in the main program, subroutines are written in a separate program.
- The main program has a single command that "calls" the subroutine program.
- A subroutine is called using M97 or M98 and a P address.
- The P code is the same as the program number (Onnnn) number of the subroutine.
- The subroutines can include an L or repeat count. If there is an L, the subroutine call is repeated that number of times before the main program continues with the next block.

Address Codes

А	Forth Axis	R	Canned cycle and circular
В	Linear B-axis motion		optional data
С	Fifth axis rotary motion	S	Spindle speed (1–99999) No
D	Canned cycle data	_	decimals allowed.
E	Feed rate	Т	Tool selection Txxyy, where xx is tool location with respect to the
F	Feed rate		turret position and yy selects the
G	Type of operation, 0 to 255. GOx		tool offset (1–50).
	are non-modal, referring only to	U	Incremental X axis motion
	that block.	V	Optional macro parameter
I, J, K	Canned cycle and circular optional data	W	Incremental Z axis motion
	•	Х	Linear X axis motion
L	Loop count for repeated cycles.	Y	Linear Y-axis motion
Μ	Control miscellaneous functions	Z	Linear Z-axis motion
Ν	Line number	Z	
0	Program number (name) Oxxxxx		
Р	Delay time		
Q	Canned cycle optional data.		

M Codes (One per Block)

- M00 Program stop (spindle, axes coolant)
- M03 Start spindle clockwise
- M04 Spindle counterclockwise
- M05 Spindle stop
- M08 Coolant on
- M09 Coolant off
- M10 Clamp spindle chuck
- M11 Unclamp spindle chuck
- M21 Tailstock forward
- M22 Reverse tailstock
- M23 Thread chamfer (G76 or G92)

M24	Thread chamfer off
M30	Program end and rewind
M41	Low gear
M42	High gear
M85	Automatic door open
M86	Automatic door close
M88	High pressure coolant off
M97	Local sub-Program call
	(P or L)
M98	Sub-program call (P or L)
M99	Return for subprogram or loop

Machine Defaults

- On power up the machine will go to part zero entered into G54 from prior probing.
- Automatic G Codes
 - G00 Rapid traverse
 - G18 X, Y circular plane section
 - G40 Cutter compensation cancel
 - G54 Work coordinate Zero #1 (1 of 26 available)
 - G64 Exact stop cancel
 - G97 Constant surface speed cancel
 - G99 Feed per revolution
- Safety line usually not used with lathe:
 - G18 G20 G40 G54 G80 G97 G99

Sample Program

G28; G53 G00 X-3. Z-4.; T101; G50 S2000; G97 S1146 M03;

G54 G00 X1.5 Z.02 M08;

G96 S450; G00 Z1. M09;

G28; G53 G00 X-3. Z-4. T0; M30; (Rapid all axis machine zero) (Safe locate tool change turret) (Indexes turret to tool) (Spindle speed max.) (Cancel surface speed mode; spindle speed; clockwise)

(Rapid movement to start X, Z; coolant on)

(Constant surface speed; surface feet per minute (SFM)) (Move from part. coolant off)

(Rapids to machine home) (Back to tool change location) (End of program. Stop spindle, turn off coolant, cancel tool length offsets)

Display Keys

Prgrm/Convrs – Active program pane . In EDIT:MDI mode, press to access VQC and IPS (if installed).

Posit (Position) – Positions pane, located in the lower center of most screens. Displays the current axis positions. Toggle between relative positions by pressing the POSIT key. To filter the axes displayed in the pane, type the letter for each axis you want to display and press WRITE/ENTER.

Offset – Toggle between the two offsets tables. Tool, radius, wear offsets, and coolant position. Select the Work Offsets table to display and edit the G-code specified work offset locations used in programs.
 Curnt Comds (Current Commands) – Press PAGE UP / PAGE DOWN to cycle through menus for Maintenance, Tool Life, Tool Load, Advanced Tool Management (ATM), Barfeeder, System Variables, Clock settings and timer / counter settings.

- Alarm / Mesgs (Alarms / Messages) Displays the alarm viewer and message screens. Pressing a second time will display a page for user messages and notes.
- Param / Dgnos (Parameters / Diagnostics) Displays parameters that define the machine's operation. A second press key will display the first page of diagnostic data.
- Setng / Graph (Settings / Graphics) Displays and allows changing of user settings. Pressing a second time enables Graphics mode. You can view the generated tool path of the program and, if necessary, debug the program before running it
 Help / Calc (Help / Calculator) Displays help topics in a tabbed menu. Available help includes brief descriptions of G and M codes,
 - definitions of control features, troubleshooting and maintenance issues. The help menu also includes several calculators.

Spindle Codes

- M03 Spindle Forward
- M04 Spindle Reverse
- M05 Spindle Stop
- G50 Maximum spindle speed (RPM revolutions per min.)
- G96 Constant surface speed ON (SFM),
 - Tool speed increases automatically as diameter decreases.
 - SFM = 0.2618 x Diameter x RPM
- G97 Constant surface speed OFF (DEFAULT) & RPM ON,
 - RPM = $\frac{3.82 \text{ x SFM}}{Diameter}$
- G98 Feed (inches) per minute, IPM = Current RPM \times IPR
- ▶ G99 Feed (inches) per revolution(DEFAULT), IRP = IPM/Current RPM

Graphics Mode



- Safest way to troubleshoot (vs. Dry Run)
- Can run from Memory, MDI, DNC or Edit
- Press the SETNG/GRAPH key.
- In Edit mode, press CYCLE START
- F1 Help key
- F2 Zoom key
- **F3 & F4** Simulation Speed.

Pendant Side Panel

USB - Plug compatible USB devices into this port.



V

Memory Lock - Keyswitch. Toggle to the lock position to protect programs and settings from alteration. Unlock to allow changes.



Setup Mode - Keyswitch. Locks and unlocks machine safety features for setup purposes (see the "Setup Mode" in the Safety section of this manual for details)



Second Home - Press this button to rapid all axes to the coordinates specified in G54 P18.



Autodoor Override - Press this button to open or close the Autodoor (if equipped).



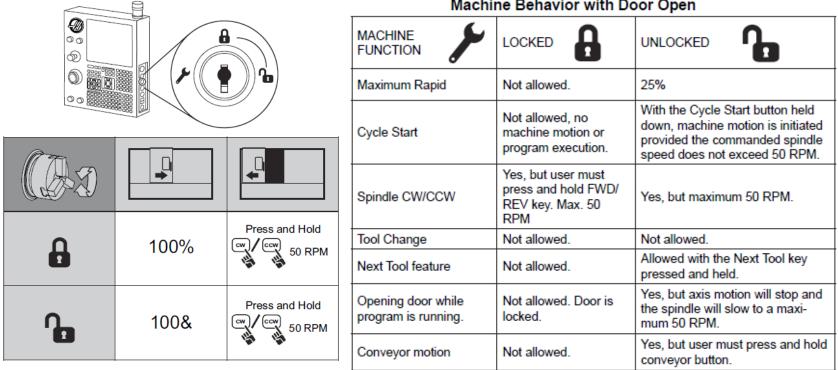
Prof. Steven S. Saliterman

Worklight - These switches toggle the internal worklight and High Intensity Lighting (if equipped).

Keyboard Beeper - Located at the top of the parts tray. The volume can be adjusted by turning the cover.

Image courtesy of Haas

Lock & Unlock Behavior



Machine Behavior with Door Open

Prof. Steven S. Saliterman

Images courtesy of Haas

Tailstock

Watch 27 m

- The optional tailstock is designed to travel to position at 2 rates. High pressure is called "rapid" and can be programmed with G00. Low pressure is called "feed" and can be programmed with G01.
- Recommended hydraulic tailstock operating pressure is 120 psi.
- Set a Restricted Zone for the tailstock with setting 93 (Tail ST. X Clearance) and Setting 94 (Z/TS Diff @ X Clearance)

Summary

- Lathe Axis and Absolute & Incremental Positioning.
- Control Pendant with Display
 - Power On; Set Up, Edit and Operating Displays
- Jog Mode
 - Function, Jog and Override Keys
- Manual Tool Offset
- Setting Part Zero
- Tool Pre-Setter with Probe
- Mode Keys
- Programming & G Codes
 - Programs, Subroutines, Address Codes, M Codes, Defaults, Safety Line
- Display Keys
- Spindle Codes
- Graphics Mode
- Pendant Side Panel & Lock and Unlock Behavior
- Tailstock

References

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