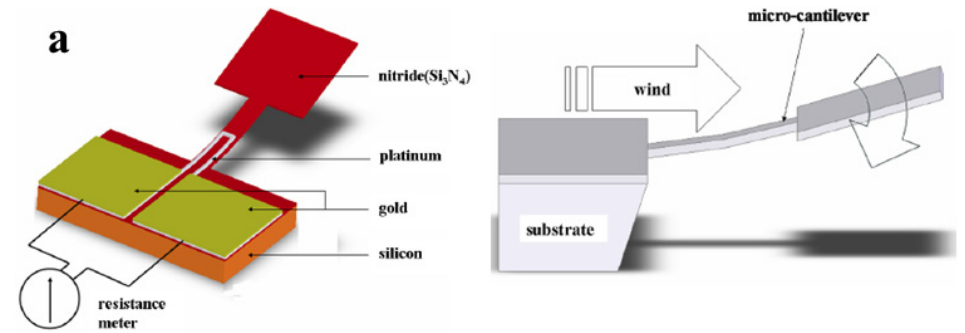
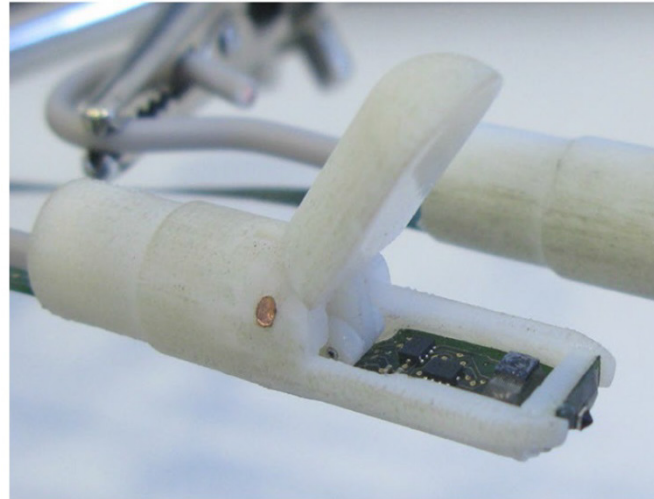
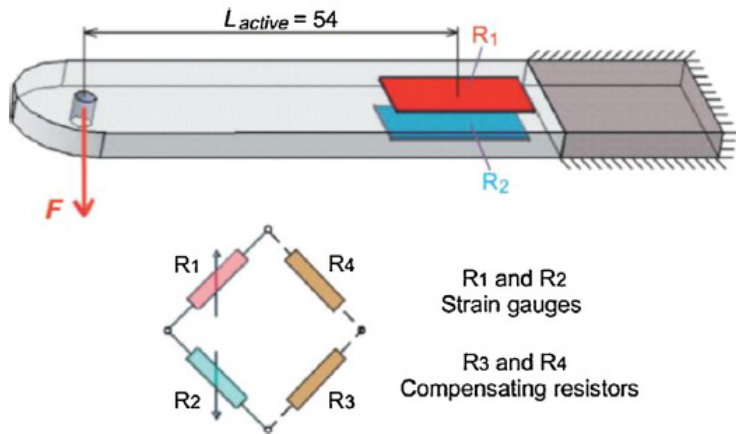


Sensor Principles

Prof. Steven S. Saliterman, <http://saliterman.umn.edu/>



Sensor Classification Schemes

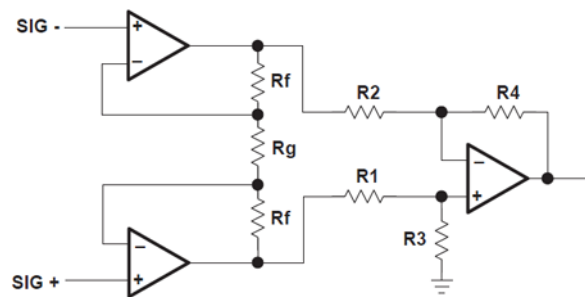
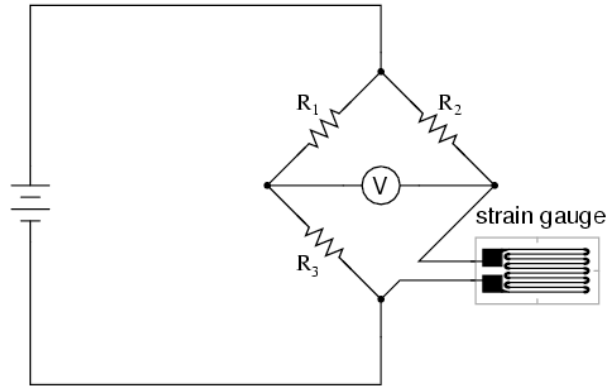
- A sensor measures information from the environment (e.g. a blood *analyte*, or *measurand*) and provides an electrical signal in response.
- Sensors may be classified in various ways:
 - **Measurand** - temperature, pressure, flow etc.
 - **Transduction** (physical and chemical effects) - SAW, ion selective FETs, optodes (chemical transducer) etc.
 - **Materials** - resistive, piezoelectric, magnetic, permeable membranes, etc.
 - **Technology** – MEMS, bioMEMS, plasmon resonance, CMOS imaging, charge coupled devices etc.
 - **Energy requirement** - active or passive.
 - **Applications** - industrial, automotive, aviation, consumer electronics, biomedical etc.

Common Microsensor Types

- **Thermal sensors** – measuring changes in temperature.
 - Thermomechanical
 - Thermoresistive
 - Thermocouples.
- **Mechanical sensors** – properties of strain, force and displacement.
 - Piezoresistive – strain in a semiconductor changes resistivity.
 - Piezoelectric – strain in a piezoelectric crystal causes a potential.
 - Capacitive – electrostatic, parallel plates and displacement.
 - Resonant – microfabricated beams and bridges.
- **Chemical sensors** – interaction with solids, liquids and gases.
- **Radiant sensors** – ionizing radiation, and visible, infrared or UV light.
- **Biosensors** - *measurement of biological analytes (another lecture).*

Wheatstone Bridge Operation

Quarter-bridge strain gauge circuit



$$V_O = [(Sig +) - (Sig -)] \times \left[\frac{R_4}{R_2} \times \left[\frac{2R_f}{R_g} + 1 \right] \right]$$

$$R_1=R_2 \text{ and } R_3=R_4$$

- If the bridge resistors have the same value, equal to the strain gauge's resistance at rest, then the voltage is zero.
- The voltage can be amplified to get a higher sensitivity for the complete circuit.
- This can be done with a high gain instrumentation amplifier
- The instrumentation amplifier inputs replace the volt meter in the top circuit.

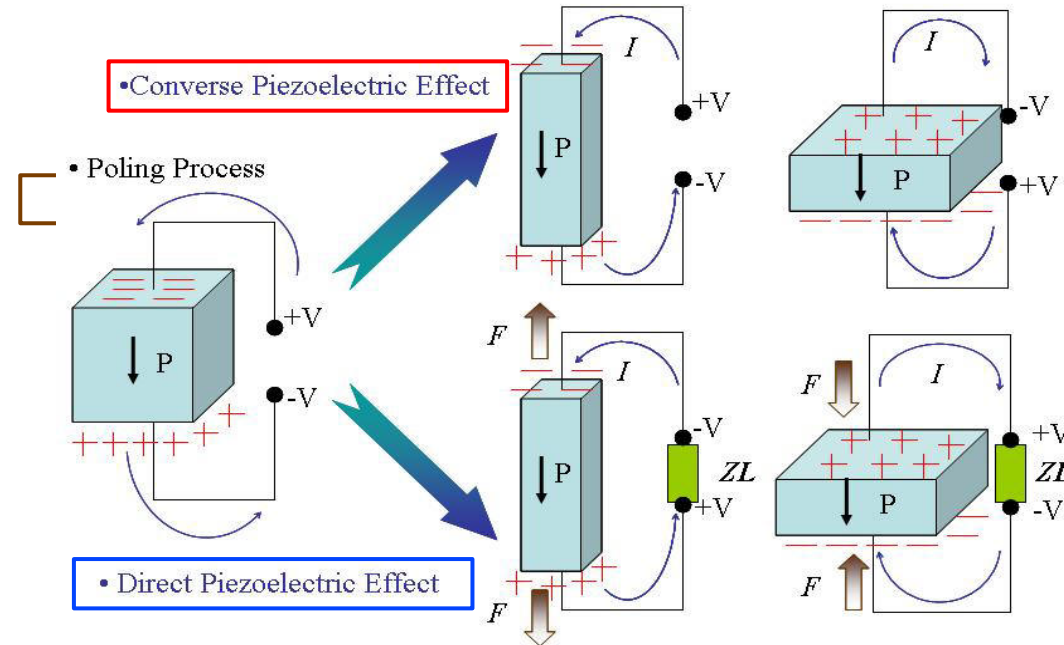
Piezoelectric Effects

- **Direct transduction** from mechanical to electrical domains and vice versa. May be used as sensors or actuators.
- The reversible and linear piezoelectric effect manifests as the production of a charge (voltage) upon application of stress (direct effect) and/or as the production of strain (stress) upon application of an electric field (**converse effect**).
- Three modes of operation depending on how the piezoelectric material is cut: **transverse**, **longitudinal** and **shear**.
- Amplifiers are needed to detect the small voltage.

Direct and Converse Piezoelectric Effects...

Converse Piezoelectric Effect - Application of an electrical field creates mechanical deformation in the crystal.

Poling - Random domains are aligned in a strong electric field at an elevated temperature.



Direct Piezoelectric Effect - When a mechanical stress (compressive or tensile) is applied a voltage is generated across the material.

Piezoelectric Relationship...

- The **piezoelectric effect** is a linear phenomenon where deformation is proportional to an electric field:

Converse Piezoelectric Effect

Direct Piezoelectric Effect

$$S = dE \quad \text{and} \quad D = dT$$

Where

S is the mechanical strain,

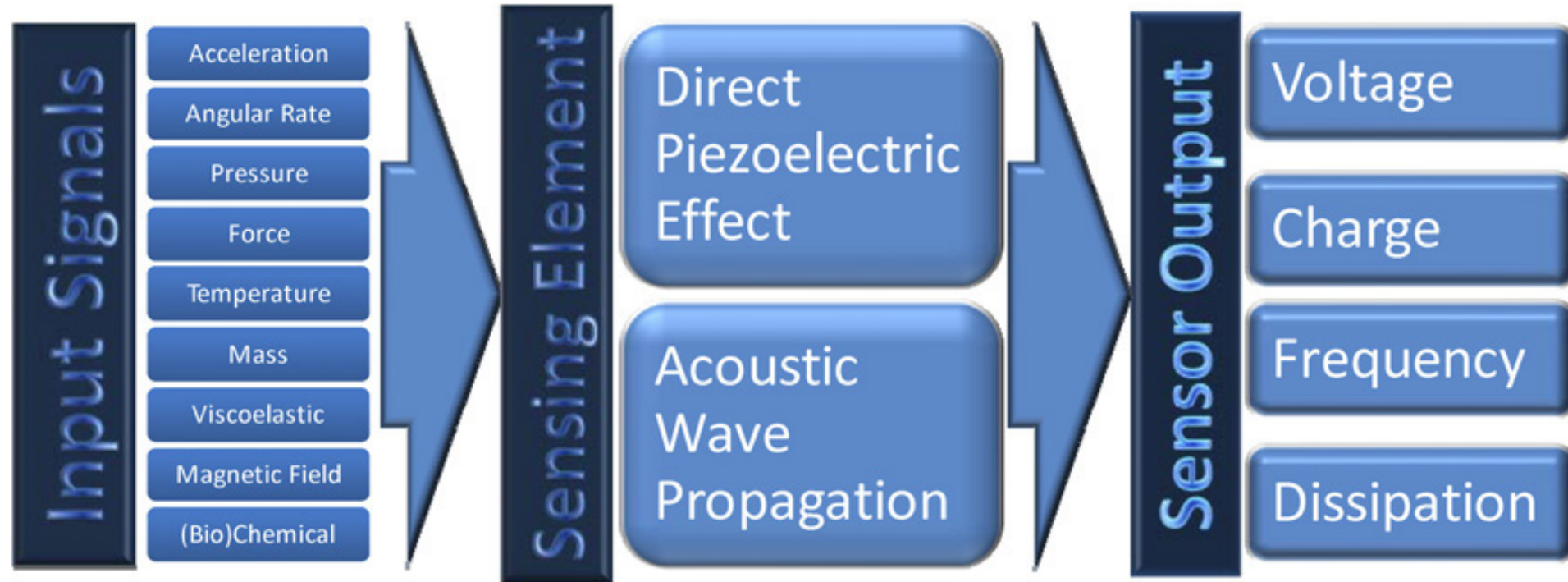
d is the piezoelectric coefficient,

E is the electric field,

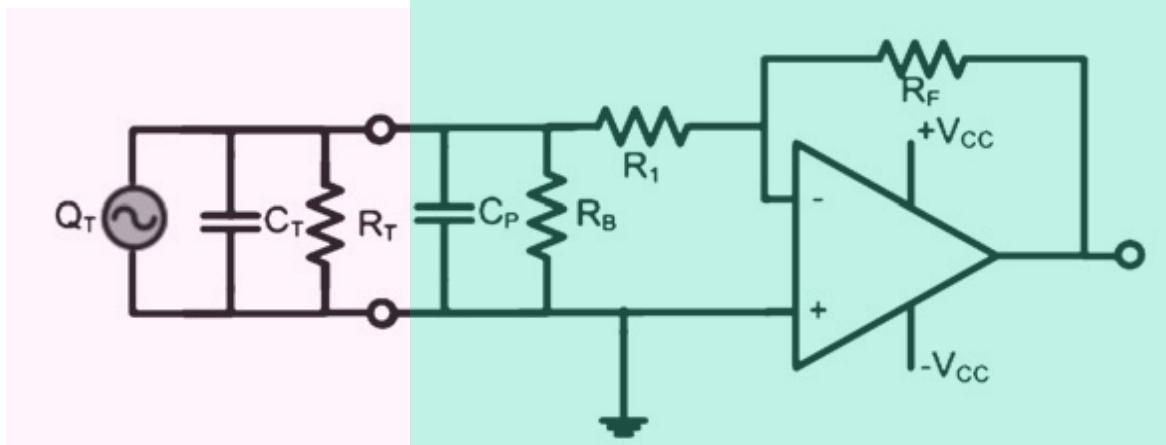
D is the displacement (or charge density) linearly, and

T is the stress.

Two Modes of Operation...

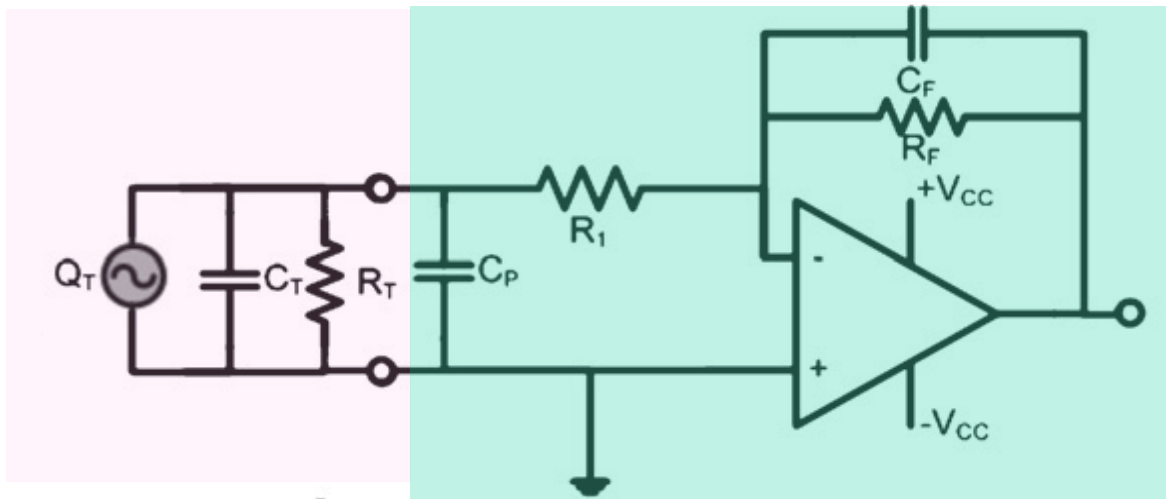


Modeling & Harnessing Piezoelectric Sensor...



Charge source Q_T with a shunt capacitor C_T and resistor R_T

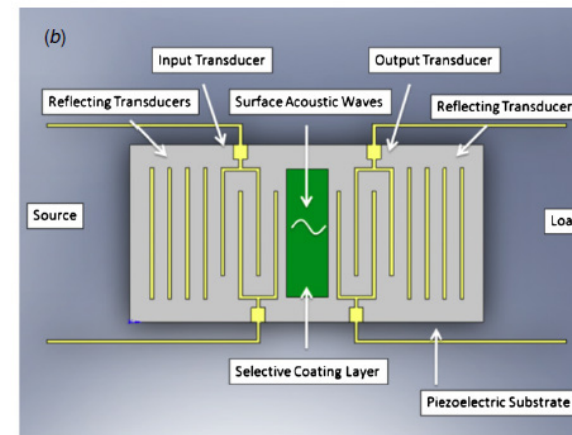
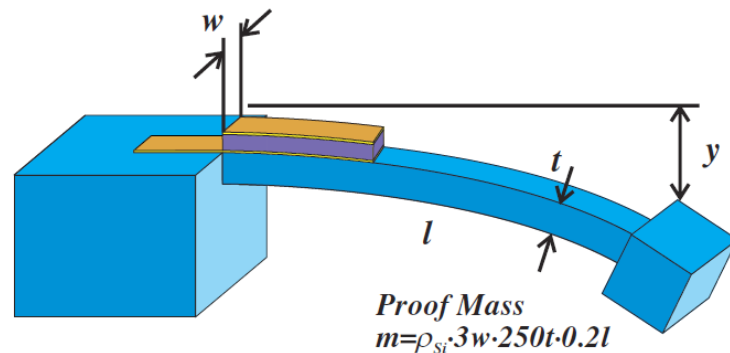
$$V_{Out} = -\frac{Q_T}{C_T + C_P} \left(\frac{R_F}{R_1} \right)$$



$$V_{Out} = -\frac{Q_T}{C_F}$$

Configurations...

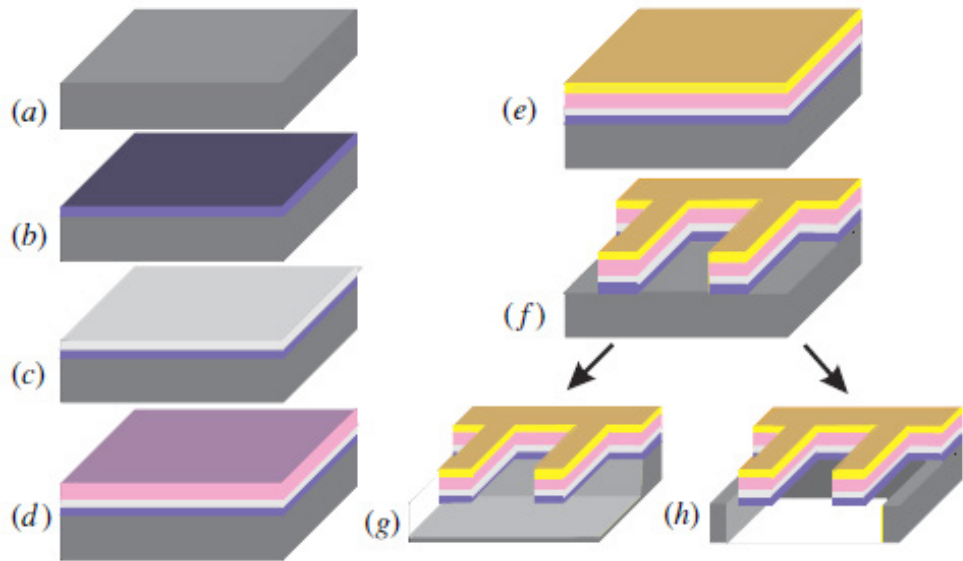
- Piezoelectric sensors may be configured as direct **mechanical transducers** or as **resonators**.
- The observed resonance frequency and amplitude are determined by the physical dimensions, material and mechanical and interfacial inputs to the device.



Piezoelectric Materials...

- **Crystals**
 - Quartz SiO_2
 - Berlinite AlPO_4
 - Gallium
 - Orthophosphate GaPO_4
 - Tourmaline (complex chemical structure)
- **Ceramics**
 - Barium titanate BaTiO_3
 - Lead zirconate titanate PZT, $\text{Pb} [\text{Zr}_x\text{Ti}_{1-x}] \text{O}_3$; $x = 0,52$
- **Other Materials**
 - Zinc oxide ZnO
 - Aluminum nitride AlN
 - Polyvinylidene fluoride PVDF

Micromachining a Piezoelectric Sensor...



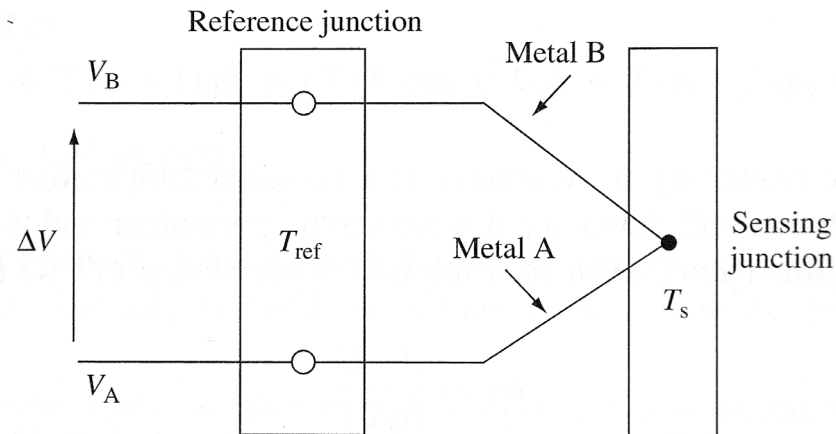
- (a) Substrate silicon wafer.
- (b) Thermally oxide placed.
- (c) Bottom platinum electrode is deposited.
- (d) The piezoelectric thin film is deposited and annealed.
- (e) Top electrode metal such as Cr/Au is deposited.
- (f) The entire piezoelectric, electrodes and passive layer stack is patterned and etched.
- (g) Substrate silicon is etched from the front side using anisotropic wet etchant or isotropic vapor phase XeF_2 etchant while protecting the transducer stack.
- (h) Alternatively, the substrate silicon is anisotropically etched from backside to release the transducer structure.

Thermosensor Basics

- **Platinum resistor:**
 - Linear, stable, reproducible.
 - Material property dependency on temperature,
- **Thermocouples (e.g. Type K)**
- **Thermistor: a semiconductor device made of materials whose resistance varies as a function of temperature.**
- Thermodiode and Thermotransistor.

Thermocouple...

- Potentiometric devices fabricated by the joining of two different metals forming a sensing junction:
 - Based on the thermoelectric *Seebeck effect* in which a temperature difference in a conductor or semiconductor creates an electric voltage:



$$\Delta V = \alpha_s \Delta T$$

Where

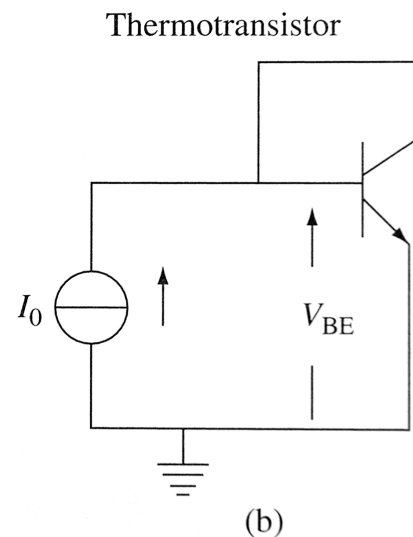
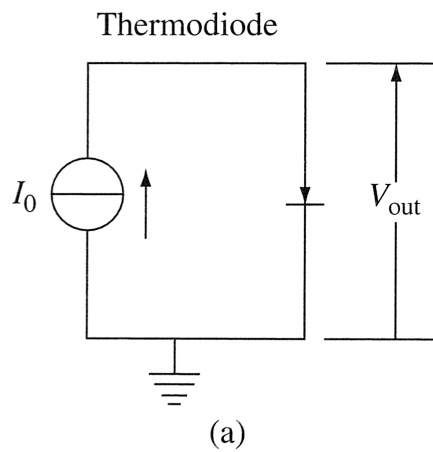
ΔV is the electrical voltage,

α_s is the Seebeck coefficient expressed in volts/ K° , and

ΔT is the temperature difference ($T_s - T_{ref}$).

Thermodiode and Thermotransistor...

- When a *p-n diode* is operated in a constant current (I_0) circuit, the forward voltage (V_{out}) is *directly proportional to the absolute temperature (PTAT)*.



$$V_{out} = \frac{k_B T}{q} \ln \left(\frac{I}{I_S} + 1 \right)$$

Where

k_b is the Boltzman constant,

T is temperature,

q is the charge on an electron,

I is the operating current and

I_S is the saturation current.

Force Sensing Methods

- Force sensing methods (examples to follow):
 - Strain gauge-based force sensor.
 - Piezoresistive force sensor.
 - Capacitive force sensor.
 - Piezomagnetic force sensor.
- Others
 - Optical force sensor (Raman spectrometer, laser interferometer, AFM, optical tweezers).
 - Vision-based force sensor.
 - Electroactive force sensor (electronic and ionic).
 - PZT force sensor (based on direct piezoelectric effect).
 - PVDF force sensor (polyvinylidene difluoride).

Calculating Young's Modulus...

Stress

$$\sigma = \frac{F}{A}$$

Where...

σ stress (Mpa),

F is the force (N),

A is the cross sectional area (mm²)

Strain

$$\epsilon = \frac{(L - L_0)}{L_0}$$

Where...

ϵ is the strain,

L is the stretched length,

L_0 is the initial length (mm)

Young's Modulus
(Stress/Strain)

$$E = \sigma / \epsilon$$

Strain Gauge...

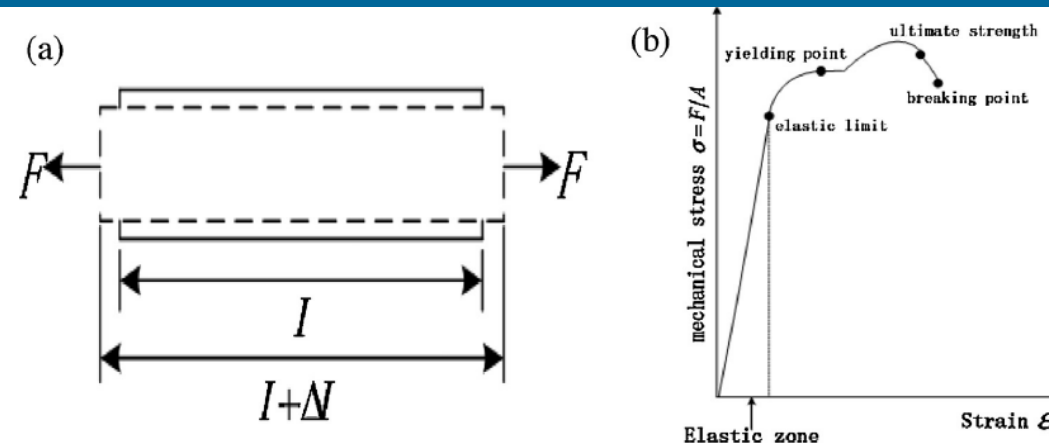


Fig. 1. Working principle of strain-gauge based force sensors. (a) Schematic diagram of strain [6], (b) stress and strain curves [6].

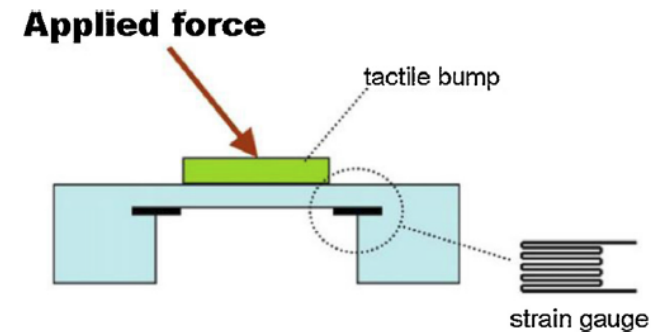
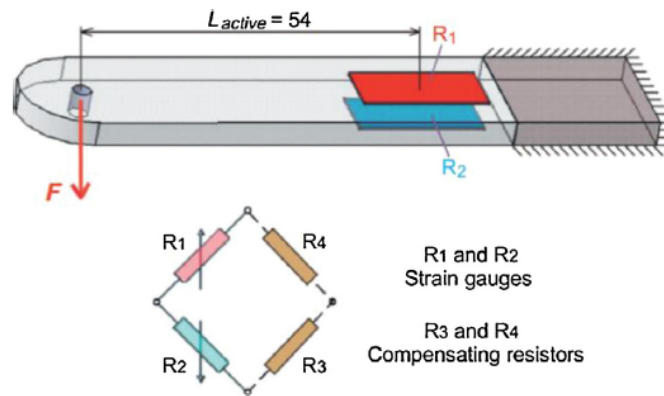
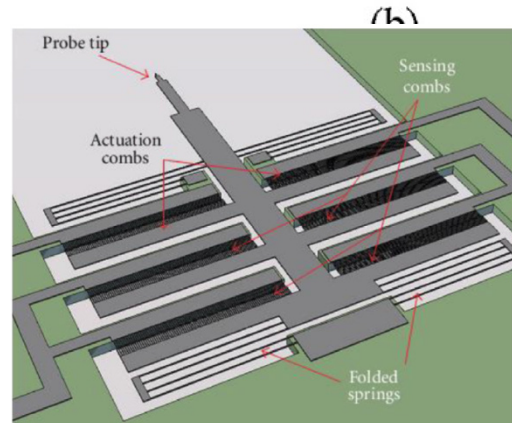
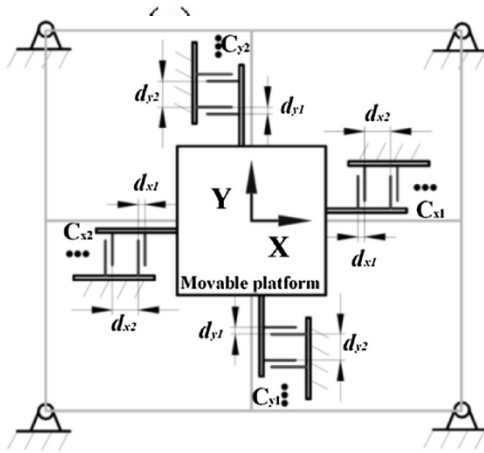
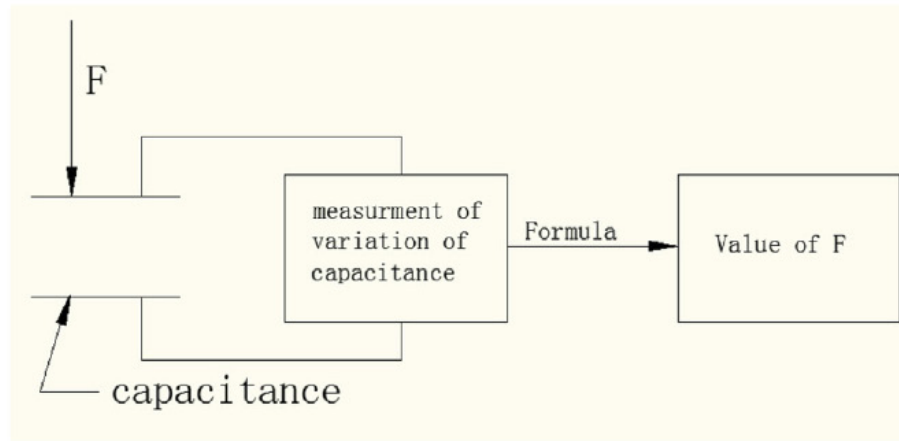
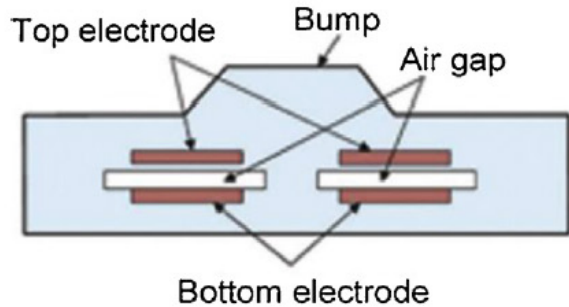


Fig. 3. An application of strain gauge-based force sensors [21].

- 1) C. Ma, J. Du, Y. Liu, Y. Chu, Overview of micro-force sensing methods, in: K.M. Lee, P. Yarlagadda, Y.M. Lu (Eds.), Progress In Mechatronics And Information Technology, 2015, Pts 1 And 22,014, 25–31.
- 2) D.M. Stefanescu, A.T. Farcasiu, A. Toader, Strain gauge force transducer and virtual instrumentation used in a measurement system for retention forces of palatal plates or removable dentures, Sens. J. IEEE 12 (2012) 2968–2973.
- 3) H. Yousef, M. Boukallel, K. Althoefer, Tactile sensing for dexterous in-hand manipulation in robotics—a review, Sens. Actuators A: Phys. 167 (2011) 171–187.

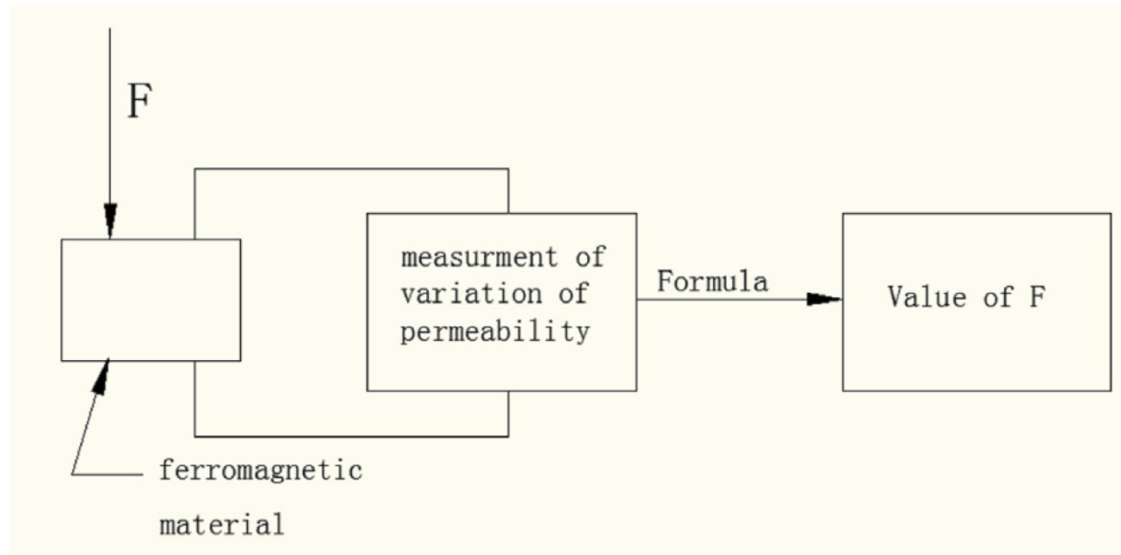
Capacitive Force Sensor...



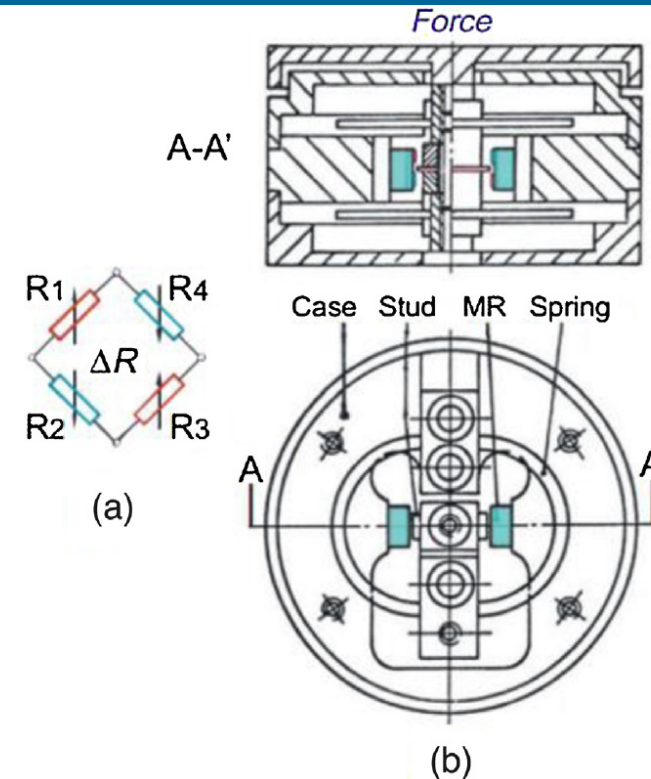
- Functions by measuring force by changes in the distance between plates.
- **Able to measure normal and shear stress.**
- Range: mN to pN.
- RC circuits may account for up to 30% of sensors.
- Signals are obtained by capacitance to frequency conversion (oscillator), switched capacitor or capacitive AC bridge circuits.

H. Yousef, M. Boukallel, K. Althoefer, Tactile sensing for dexterous in-hand manipulation in robotics—a review, *Sens. Actuators A: Phys.* 167 (2011) 171–187.
 S. Nadvi, D.P. Butler, Z. Celik-Butler, I.E. Goenenli, *Micromachined force sensors using thin film nickel-chromium piezoresistors*, *J. Micromech. Microeng.* 22 (2012).
 L. Zhang, J. Dong, *Design, fabrication, and testing of a SOI-MEMS-Based active microprobe for potential cellular force sensing applications*, *Adv. Mech. Eng.* (2012).

Piezomagnetic Force Sensor...



- **Magnetoelastic effect** - when a ferromagnetic material is subjected to mechanical stress, its internal strain leads to changes in permeability.
- Dynamic and static force measurements.
- Does not need to be glued to the surface.



Wheatstone bridge configuration with magnetoresistive sensors. Resistance varies with magnetic field strength.

Flow Sensors

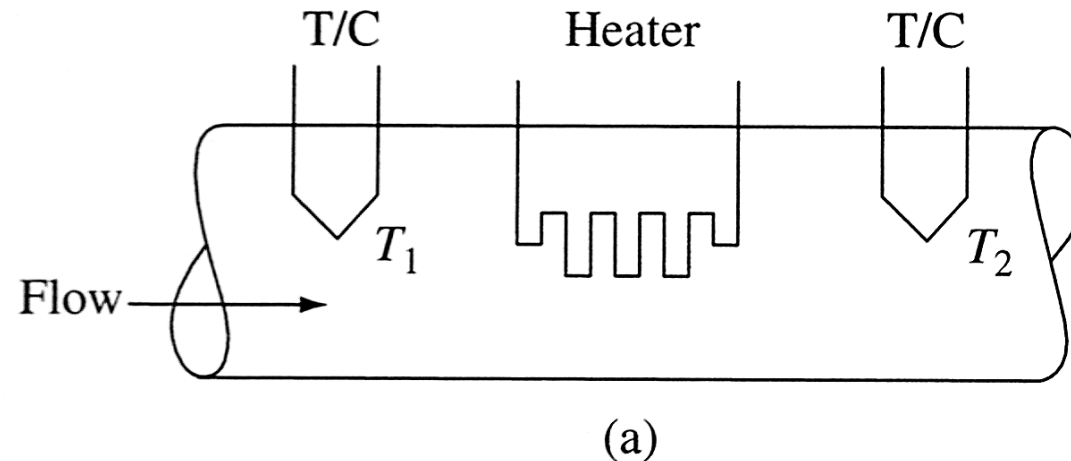
- Measurement of gas and liquid flow rates.
- May be integrated with microfluidics.
- Useful for blood and urine flow, respiratory monitoring and drug delivery devices.
- Advantages of high sensitivity, accuracy and precision, low power consumption and small size.
- Broadly categorized as thermal (thermal exchange) and non-thermal flow sensors.

Thermal Flow Sensing...

- **Hot wire or hot element anemometers.**
 - Based on **convective heat exchange** taking place when the fluid flow passes over the sensing element (hot body).
 - Operate in constant temperature mode or in constant current mode.
- **Calorimetric sensors.**
 - Based on the monitoring of the **asymmetry of temperature profile around the hot body** which is modulated by the fluid flow.

Example of a Thermal Flow Sensor...

- The heat transferred per unit time from a resistive wire heater to a moving liquid is monitored with a thermocouple:



- In a steady state, the mass flow rate can be determined:

$$Q_m = \frac{dm}{dt} = \frac{P_h}{c_m} (T_2 - T_1)$$

Where

Q_m is the mass flow rate,

P_h is the heat transferred per unit time,

c_m is the specific heat capacity of the fluid and

T_1, T_2 are temperature.

- The volumetric flow rate is calculated as follows:

$$Q_V = \frac{dV}{dt} = \frac{Q_m}{\rho_m}$$

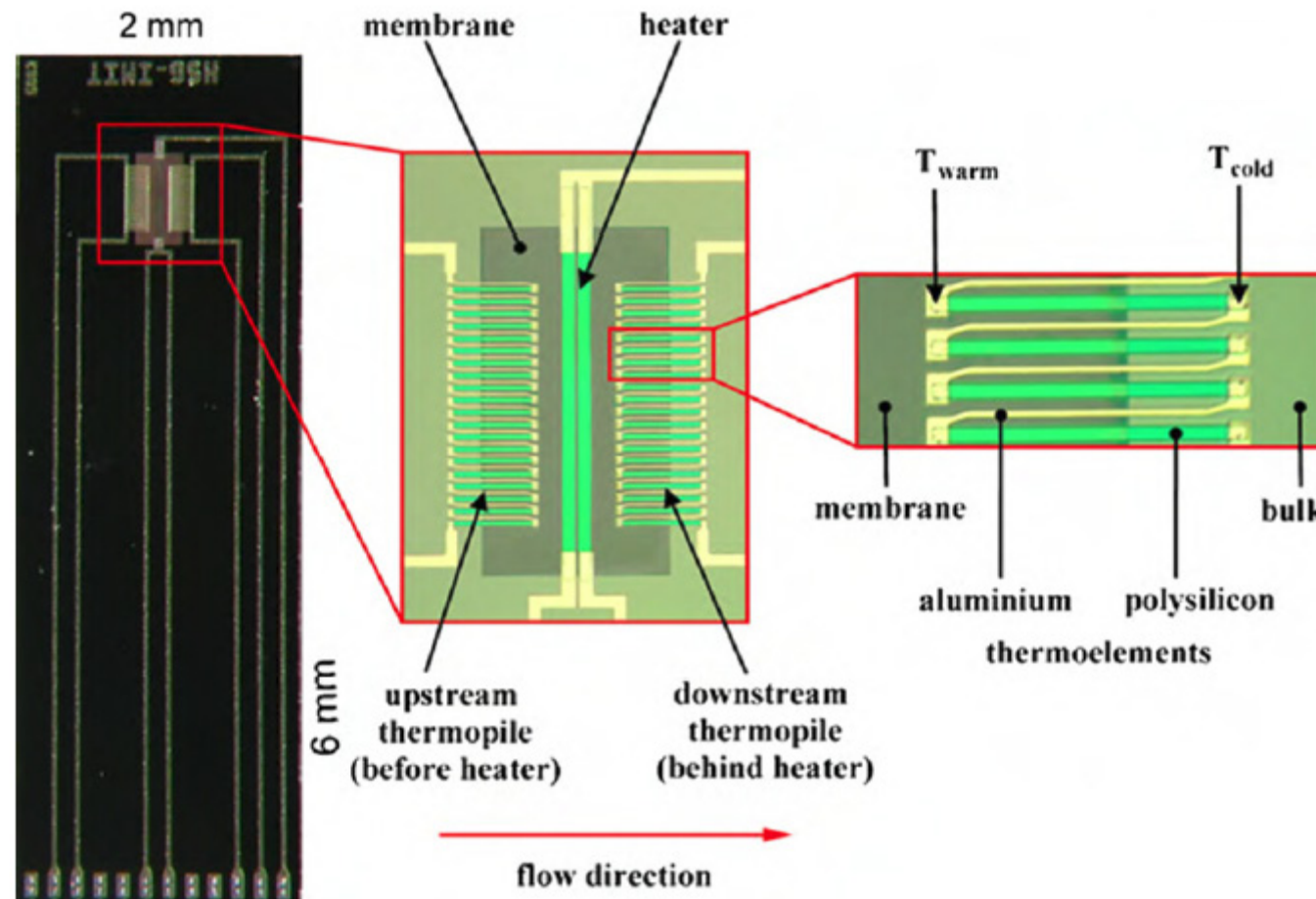
Where

Q_V is the volumetric flow rate,

Q_m is the mass flow rate and

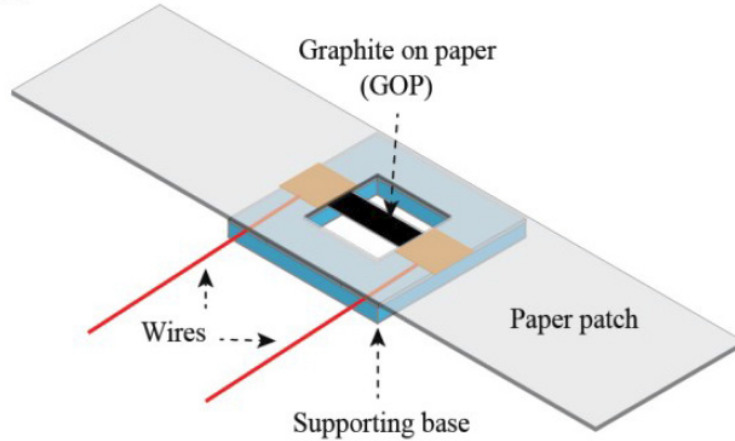
ρ_m is the density.

Thermal Flow Sensor with Thermopile...

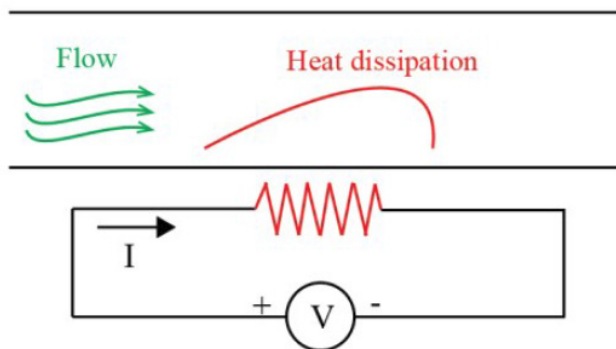


Pencil Graphite Thermal Flow Sensor...

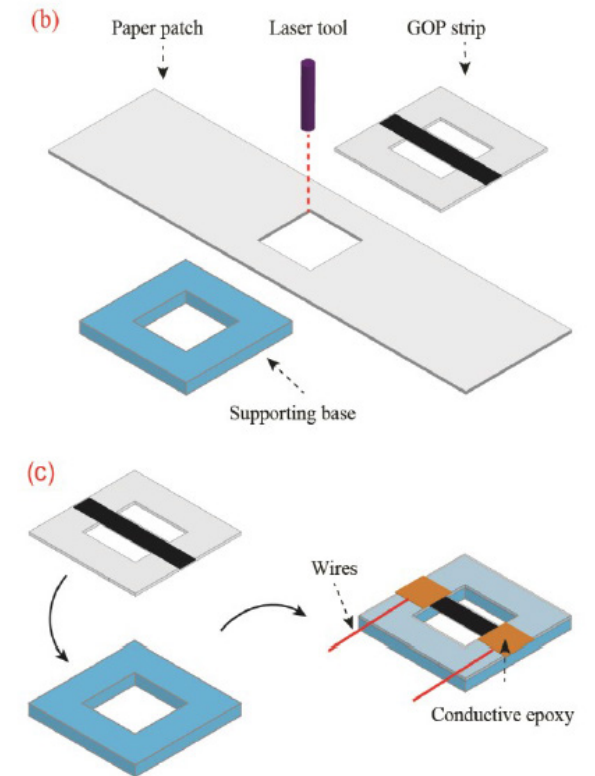
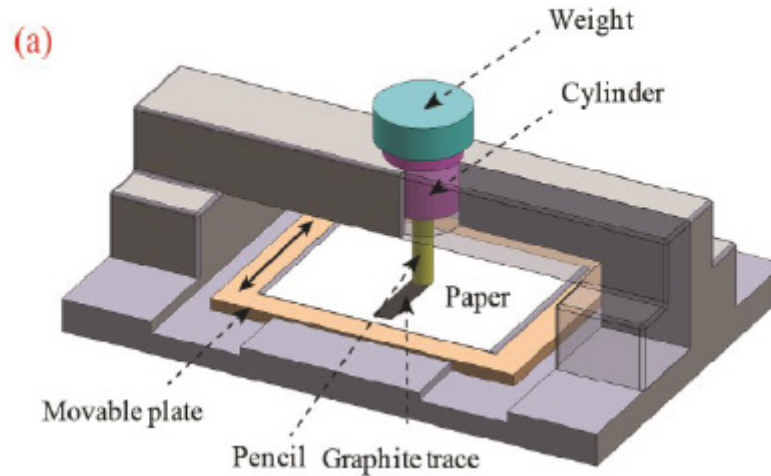
(a) Structure of the sensor

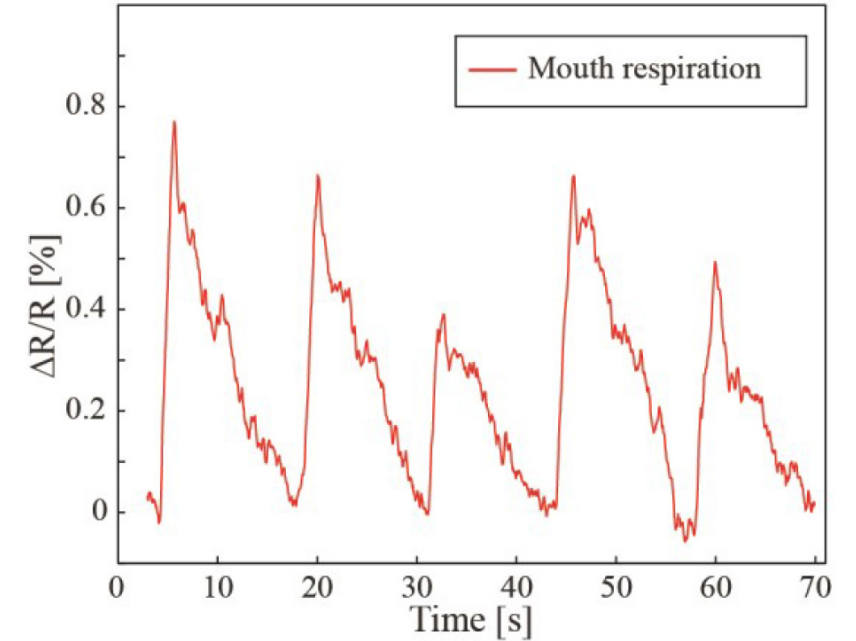
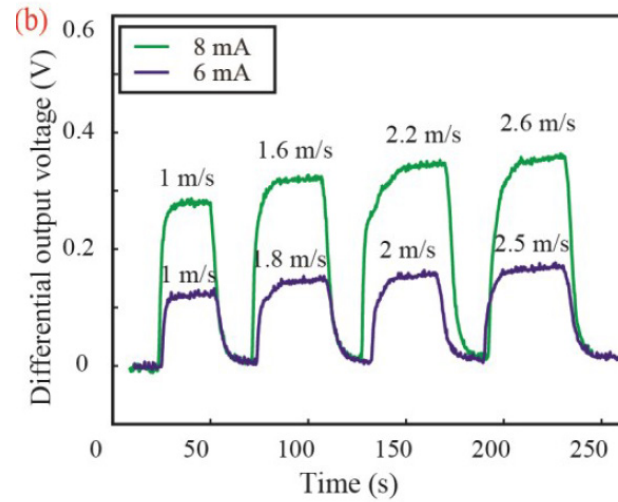
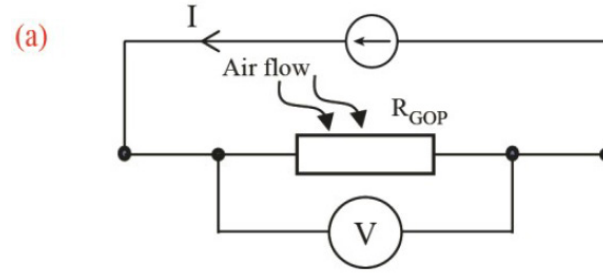
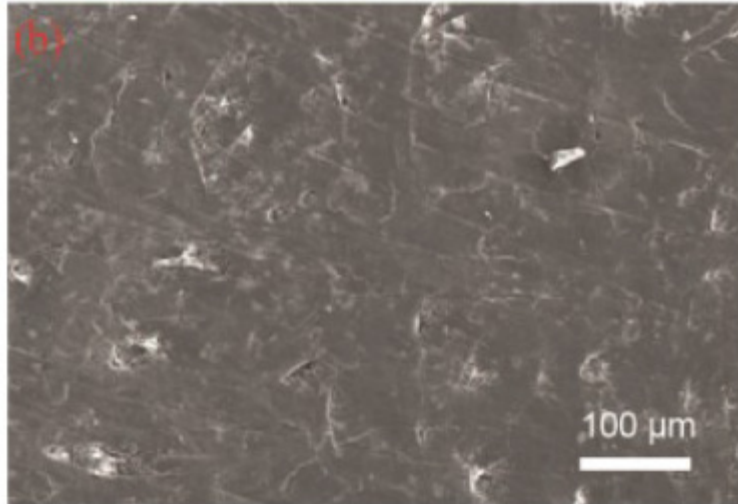
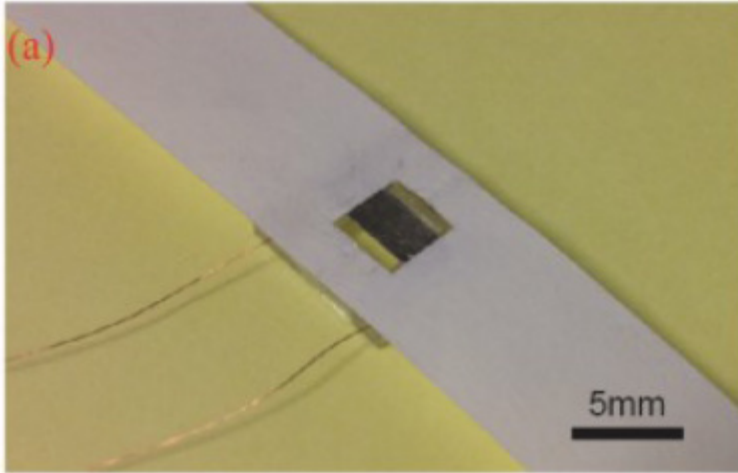


(b) Working principle of the sensor



Fabrication process





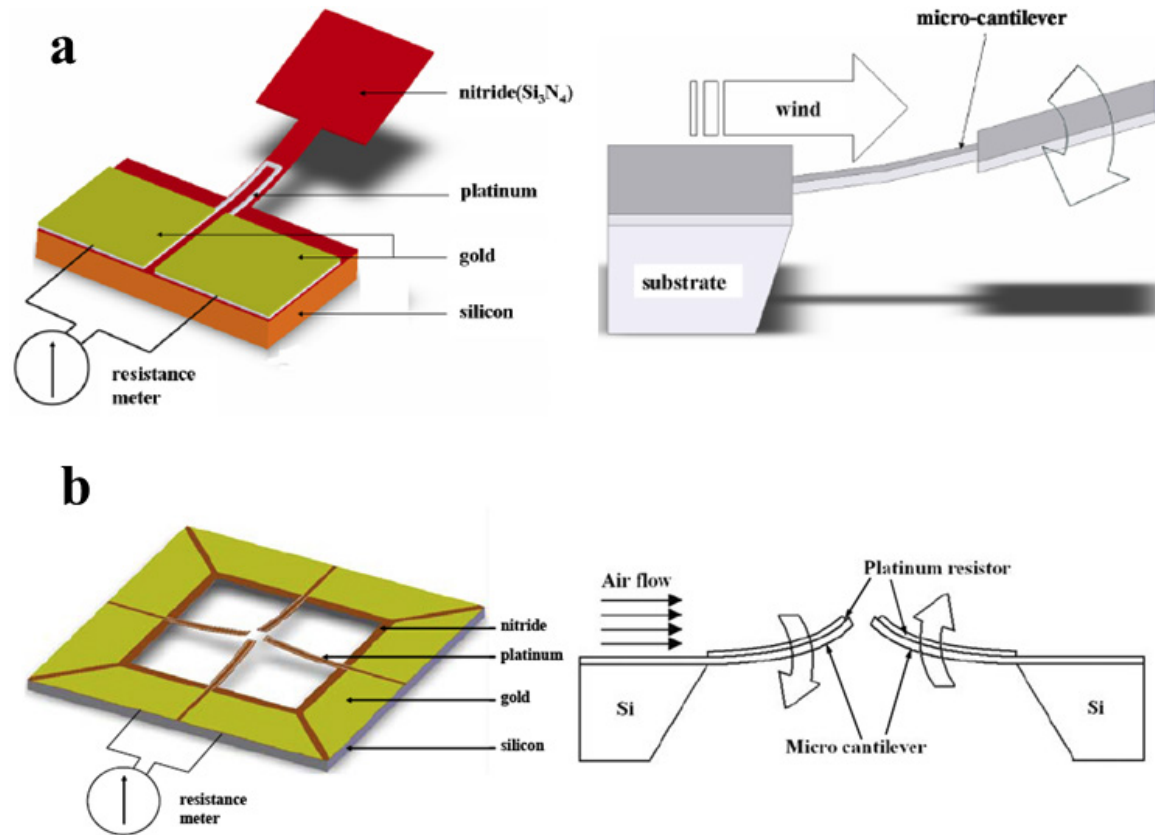
- Constant current applied.
- Voltage changes with changes in air flow rate.

Human respirations.

Non-Thermal Flow Sensors

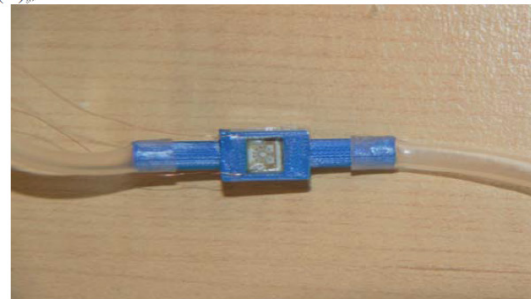
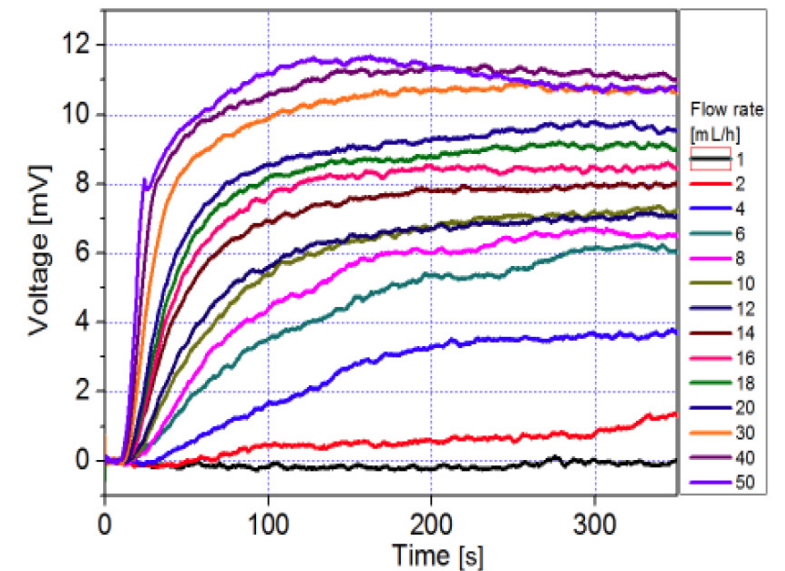
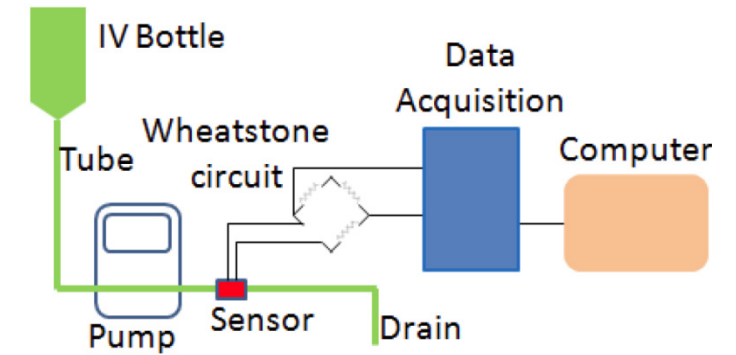
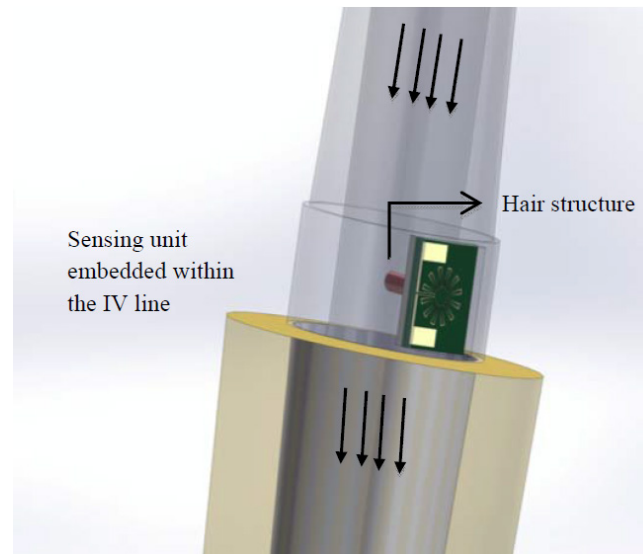
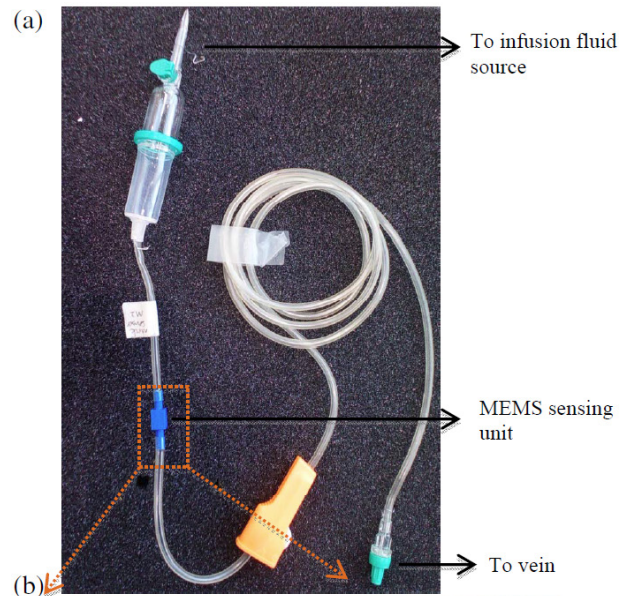
- **Cantilever type flow sensors**
 - Measuring the drag-force on a cantilever beam.
- **Differential pressure-based flow sensors**
 - When a fluid flow passes through a duct, or over a surface, it produces a pressure drop depending on the mean velocity of the fluid.
- **Electromagnetic**
- **Laser Doppler flowmeter**
 - The phenomenon is due to the interaction between an electromagnetic or acoustic wave and a moving object: the wave is reflected back showing a frequency different from the incident one.
- **Lift-force and drag flow sensors**
 - Based on the force acting on a body located in a fluid flow.
- **Microrotor**
 - Rotating turbine
- **Resonating flow sensors**
 - Temperature effects resonance frequency of a vibrating membrane.

Cantilever Type Sensor...

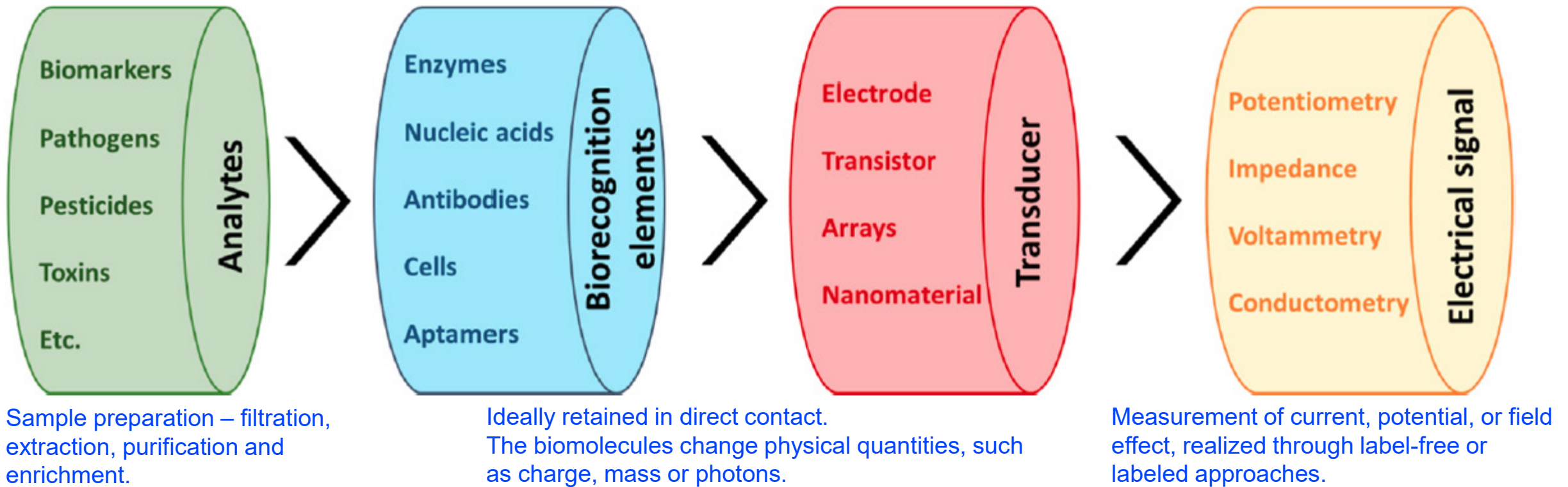


Able to Sense Direction

Intravenous Infusion Flow Sensor...



Electrochemical Biosensing



Analytes are detected with *biological recognition elements*, including enzymes, nucleic acids, antibodies, cells and aptamers. *Electrical signals* are derived from *transducers*, including electrodes, field effect transistors (FETs), arrays and nanomaterials.

Applications in Medicine

- Glucose and anticoagulation monitoring:



● Temperature:

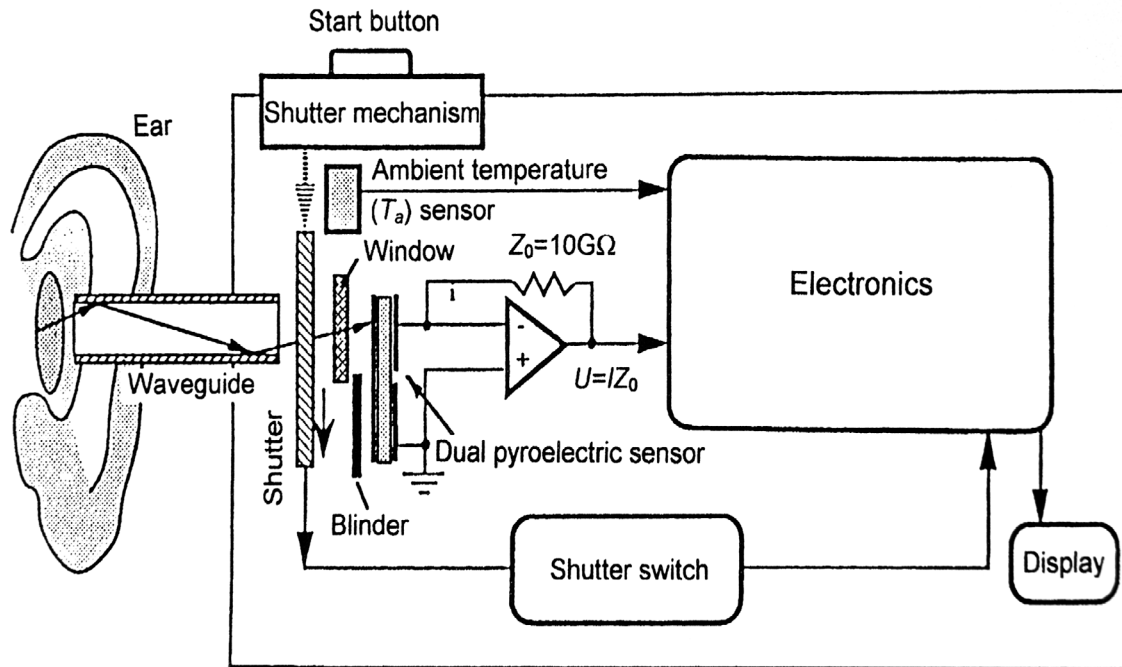
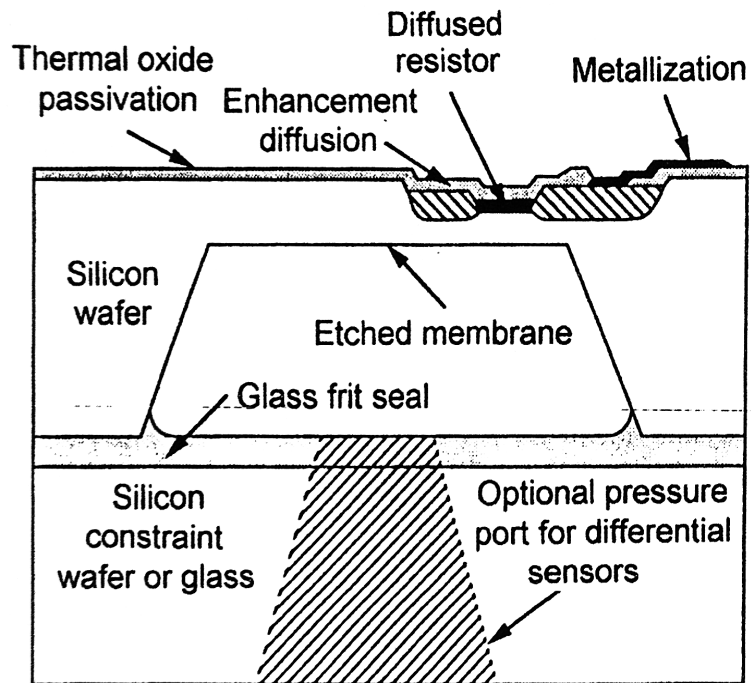
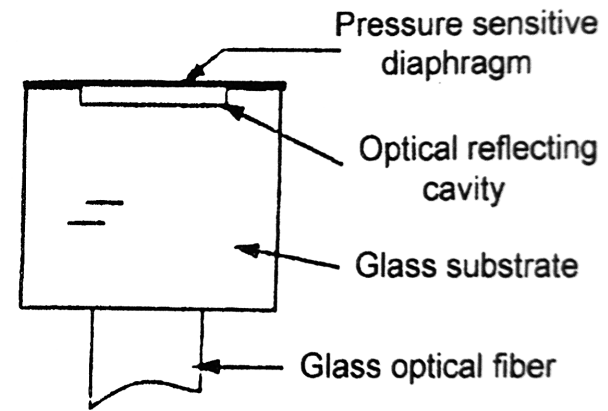


Image courtesy of Braun

● Pressure:

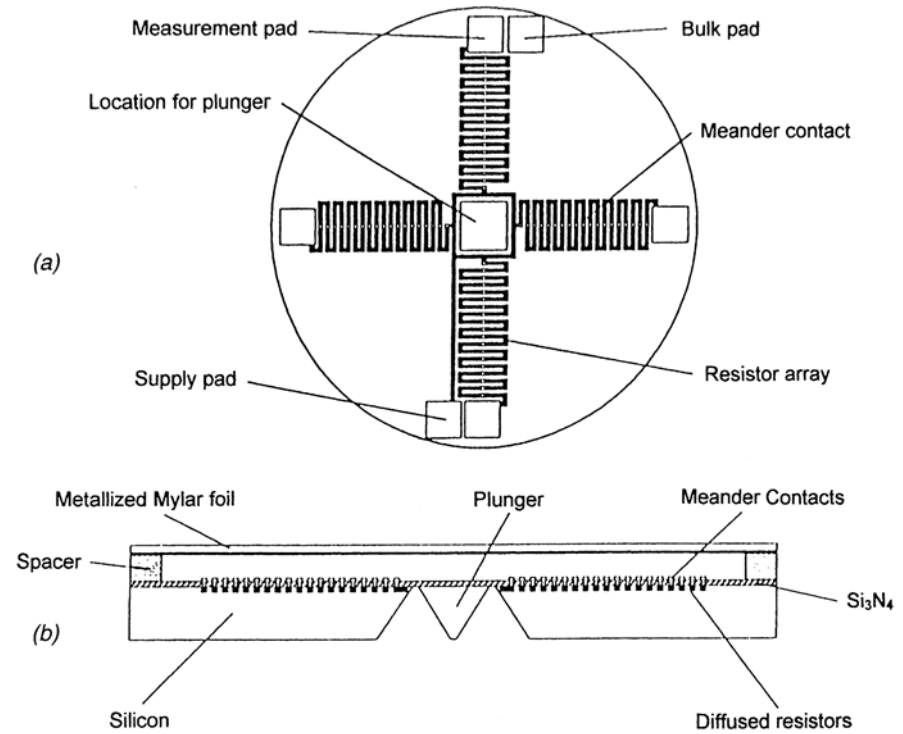
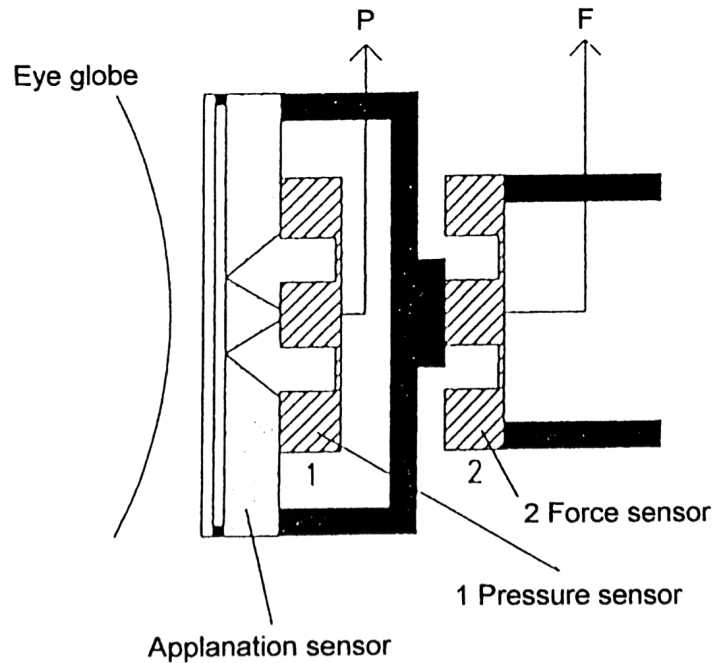


(a)



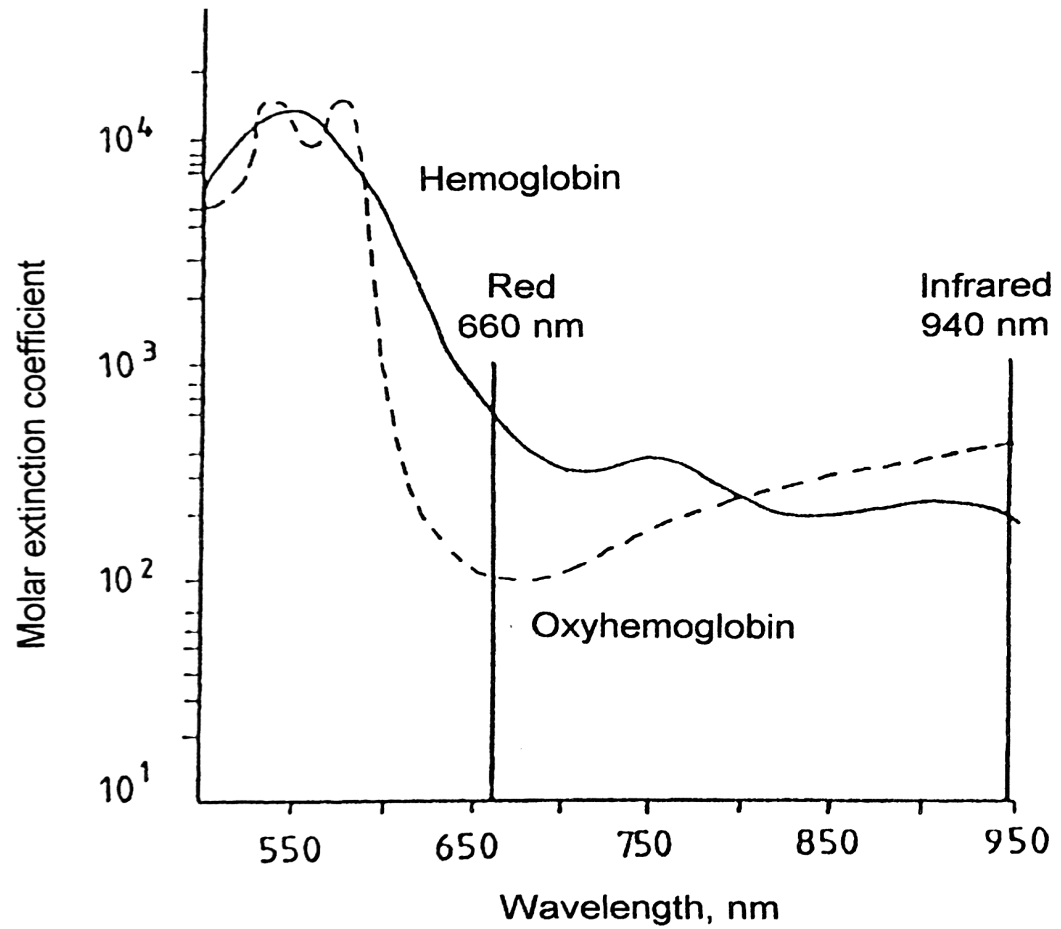
(b)

- Intraocular pressure:

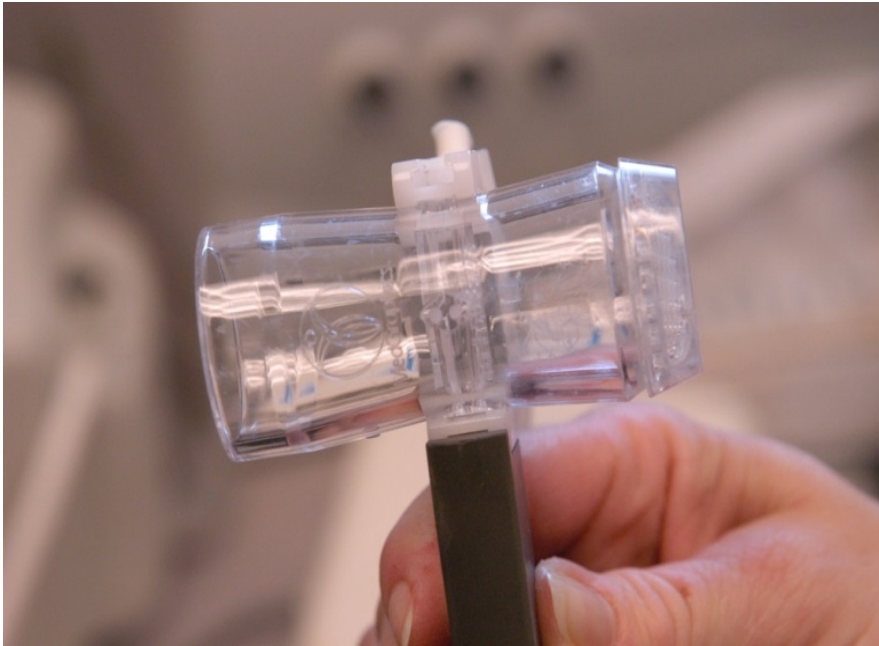


- Pulse oximetry:





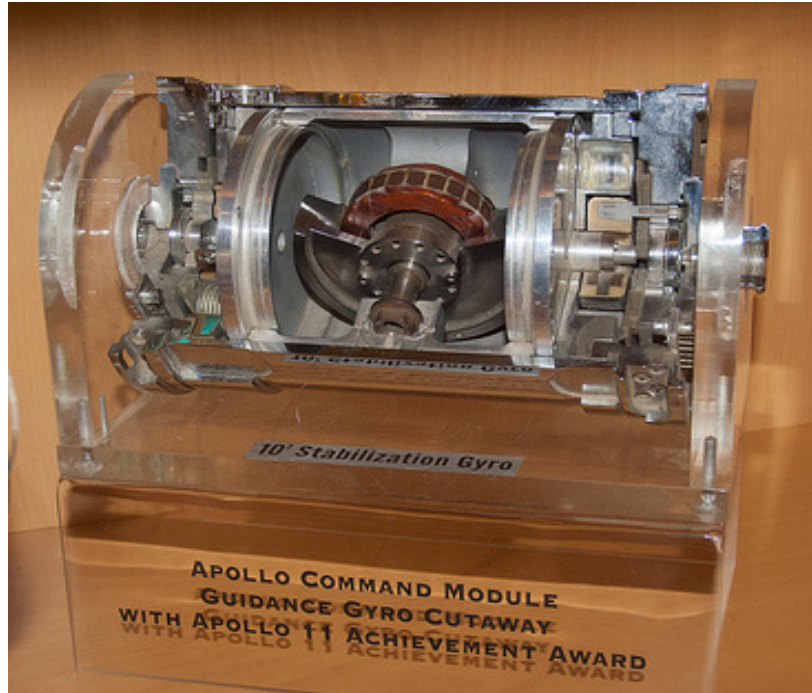
- Respiratory – spirometry and CO₂:



- Implanted pacemaker and rhythm monitor:



Position Sensing – Gyroscope Evolution

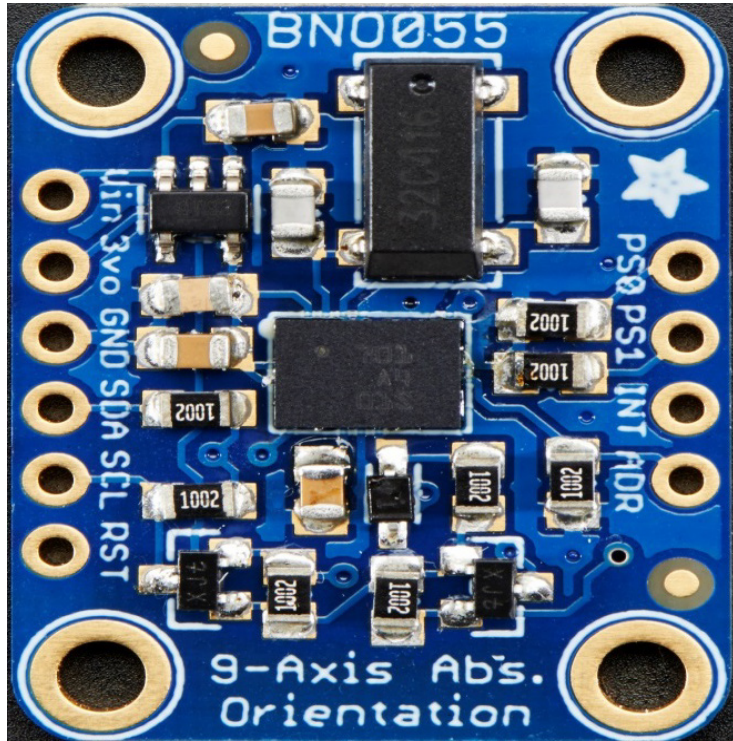


Apollo 11 Gyroscope 1969



Apollo Command Module 1973,
Johnson Space Center, Prof. Saliterman

Adafruit BN0055 – Sensor Fusion...



- **Absolute Orientation** (Euler Vector, 100Hz) Three axis orientation data based on a 360° sphere.
- **Absolute Orientation** (Quaternion, 100Hz) Four point quaternion output for more accurate data manipulation.
- **Angular Velocity Vector** (100Hz) Three axis of 'rotation speed' in rad/s.
- **Acceleration Vector** (100Hz) Three axis of acceleration (gravity + linear motion) in m/s^2 .
- **Magnetic Field Strength Vector** (20Hz) Three axis of magnetic field sensing in micro Tesla (μT).
- **Linear Acceleration Vector** (100Hz) Three axis of linear acceleration data (acceleration minus gravity) in m/s^2 .
- **Gravity Vector** (100Hz) Three axis of gravitational acceleration (minus any movement) in m/s^2 .
- **Temperature** (1Hz) Ambient temperature in degrees celsius.

Summary

- A sensor measures information from the environment (e.g. a blood *analyte*, or *measurand*) and provides an electrical signal in response.
- Sensor types introduced today:
 - Wheatstone Bridge
 - Piezoelectric
 - Thermosensors
 - Force & Microforce
 - Flow – Thermal & Non-Thermal Methods
 - Electrochemical Biosensors
 - Position Sensors
- Clinical Applications